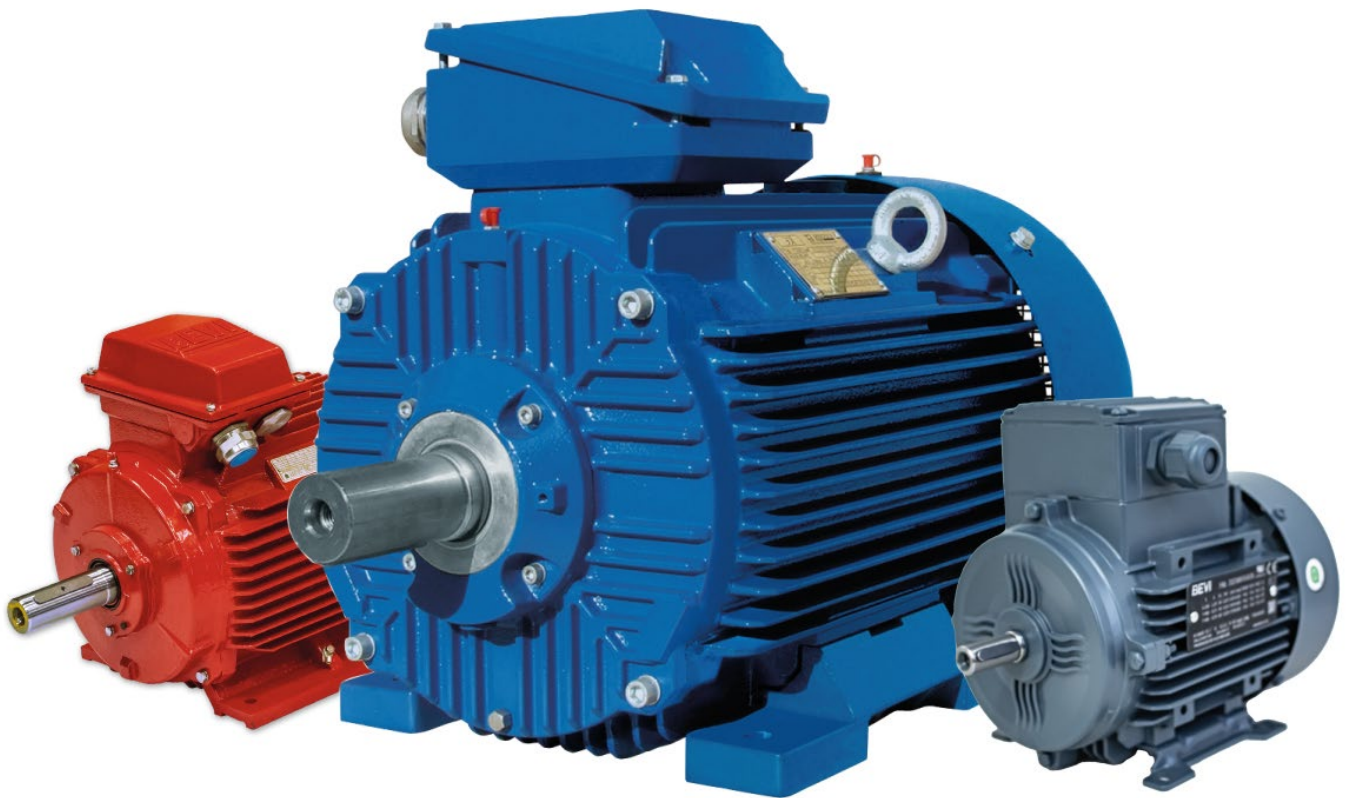


BEVI Electric motors, IEC 56-400

Installation and service instruction



Every care has been taken to ensure the accuracy of the information contained in this publication.

Due to BEVI's policy of continuous development and improvement, BEVI reserves the right to supply products which may differ slightly from those illustrated and described in this manual.

Descriptions and technical features listed in this manual may not to be considered as binding. Under no circumstances should be considered as a contractual obligation.

The data in this manual may change without prior notice.

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1 Technical description

The persons who are in contact with the motor when installing, operating or maintaining it must follow this manual. Only qualified personnel are allowed to handle the motor. If this – including health and safety regulations – are not followed, no warranty issues will be approved by BEVI.

1.1 General

This manual covers BEVI asynchronous surface-cooled induction three phase motors, single and multiple speed as well as single-phase motors, series;

- Sh, 2SIE, 3SIE, 4SIE, SEMh, 3SSIE
- 3D, 3D2, 3D3, 3D4, 3D5
- 4A, 4A2, 4A3, 4A4, 4D, 4D2, 4D3, 4D4
- 3DT, 3DT2, 3DT3, 3DT4
- 2EL, 3EL, 4EL, 3EC, 2EG, 3EG, 4EG

The motor's technical specifications are available on www.bevi.com.

All BEVI motors meets the requirements of ISO-standards and the IEC regulations and recommendations available.

If not given otherwise the rated powers are valid for continuous S1 duty, at given supply voltage and frequency, ambient temperature -20°C - +40°C and for motor setting up to an altitude of 1000m above sea level. The motors are for fixed installation only.

1.2 Enclosure

Motors are produced with degree of protection class IP55 as standard. Motors can, without special enclosure modifications, be installed outdoors and the standard paint finish is also suitable. However, for harsh environments and climatic conditions we recommend a special paint finish. Motors mounted with shaft vertically down should be protected by a canopy (rain cap) fitted over the fan cowl to prevent water from following the motor shaft into the motor. For the same reason motors mounted with shaft vertically up should be protected so that water cannot penetrate down the motor shaft. Customized motors can be ordered for IP56, IP65 or IP66 as well.

1.3 Cooling

As standard, cooling is supplied by a fan fitted onto the non-drive (ND) end shaft extension (standard designation IC411). Other cooling methods can be supplied, for example a separate blower (IC416 – forced cooling) fan which is commonly required for inverter driven motors. Note that DT-motors have cooling designation IC418.

1.4 Insulation

All motors conform to the insulation class F unless the mark plate says differently. Motors with Class F can normally be used in wet and dry tropical climate conditions. If the motor needs to comply with especially tough demands, it can be made in special executions for wet alternative dry tropical climate conditions, higher ambient temperatures etc.

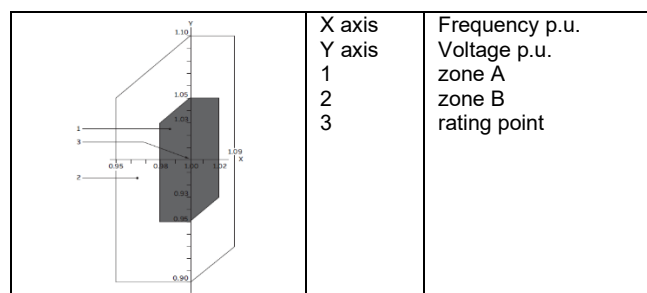
As an option the motor can be delivered with class H insulation. DT-motors are equipped with class H as standard.

1.5 Voltage and frequency

BEVI motors can be produced for frequencies of 50 and 60 Hz and all standard voltages up to 690 V. Please look on your motor data plate for actual voltage and frequency.

The impact on temperature rise caused by voltage and frequency fluctuation is defined in IEC 60034-1. The standard divides the combinations into two zones, A and B. Zone A is the combination of voltage deviation of +/-5 % and frequency deviation of +/-2 %. Zone B is the combination of voltage deviation of +/-10 % and frequency deviation of +/-5 %. This is illustrated in figure below.

Motors can supply the rated torque in both zones A and B, but the temperature rise will be higher than at rated voltage and frequency. Motors can be run in zone B only for a short period of time.



1.6 Surface

BEVI motors are painted with industrial paint as standard, but better painting process is an option, up to CX according to ISO 12944.

1.7 Terminal box and terminals

Motors in the basic execution have six terminals in the terminal box, connected to the stator windings. Multiple speed motors are provided with six or more terminals. The designation of terminals and connection diagram are given on a plate arranged inside the cover of the terminal box.

Motors with thermal protection or with heaters have separate terminals inside the terminal box. There can also be cases when an additional connection strip is provided for connection of this equipment.

1.8 Motor dewatering (drain holes)

Depending on motor size and motor group most of the BEVI motors have drain holes for dewatering the interior of the motor when so is needed. The holes are plugged with a screw or rubber plug and can be removed when needed.

Type Sh, 2SIE, 3SIE, 4SIE and SEMh has drain holes on sizes 56-80 and 132-315.

Type 3D, 3D2, 3D3 and 3D4 has drain holes from size 250 and up.

All other motors can be ordered with drain holes when required as option.

2 Standards and directive

Motor construction, dimensions and outputs comply with the International Standards and directive;

Standard	
IEC 60034-1	Rating and performance
IEC 60034-2-1	Methods for determining losses and efficiency
IEC 60034-5	Classification of degrees of protection
IEC 60034-6	Methods of cooling
IEC 60034-7	Symbols of construction and mounting arrangements
IEC 60034-8	Terminal markings and direction of rotation
IEC 60034-9	Noise limits
IEC 60034-11	Built-in thermal protection
IEC 60034-14	Vibration limits
IEC 60034-17	Cage induction motors when fed from converters
IEC 60034-18-1	Functional evaluation of insulation system
IEC 60034-30-1	Efficiency classes (IE-code)
IEC 60038	Standard voltages
IEC 60072-1	Dimensions and output series
EU-directive	
2014/35/EU	Low Voltage Directive (LVD)
2009/125/EC	Ecodesign requirements for electric motors
2011/65/EU 2015/863/EU	RoHS directive – “Restriction on Hazardous Substances”
2006/42/EC ¹	MD – Machinery Directive

Table 1 - Standards and directive

¹ By design motors are considered as components. Confirmative to the requirements of 2006/42/EC – Machinery Directive, provided

that the installation is set up correctly by the manufacturer of the machine where the motor is placed.

3 Safety information

To avoid accidents during installation, service and inspections of the motor the following work safety principles must be observed:

- The motor must be installed by a qualified electrician, in accordance with the generally in force electrical code principles and regulations.
- Be observant that the motor can have a hot surface, both during operation and after shut-down.
- In no case may the motor operate without protective guards foreseen by the motor construction.
- The coupling or belt drive must be shielded properly protected against touching.
- The motor must be suitably earthed.
- Cables and supply conductors must be properly protected against damaging.
- Do not open terminal box when energized.

Inspections, maintenance, or repairs can be done only upon order and under supervision by appropriately qualified and trained staff in the line of work safety regulations.

Inspections and repairs must take place when the motors are safely disconnected from the mains.

4 Handling

4.1 Reception of motor

When the motor has arrived, directly check the motor for damages that could have occurred during the transport.

After that, be ensured that correct motor has been delivered by checking motor data plate – type description, power, speed, connection, voltage, frequency etc.

4.2 Transport and storage

The motors can be forwarded in any covered transport means free of violent shocks or blows.

Motors with NU roller bearings should have the shaft secured during transport.

Storage of motors can take place in rooms in which:

- max. relative humidity does not exceed 80% at +20°C,
- ambient temperature ranges from -10°C to +40°C, non-condensing.
- there is no access of dusts, gases and caustic vapours as well as other corroding chemical fumes destructive to insulation or casing,
- no vibrations occur.

On the stored motors the machined surfaces should be protected against atmospheric influences by coating them with thick grease or easily removable anticorrosive lacquer. When stored the shaft should be rotated periodically to exercise bearings and grease.

4.3 Lifting of motors

Motors are heavy, when lifting or handling the motor – make sure that no person risks to come under the lifted motor.

When lifting drive units always use lifting handles designed for this purpose.

BEVI motors with a weight over 25 kg are supplied with lifting eye or similar. The lifting eye is dimensioned to lift the motor, if the motor is mounted on other equipment, the motor's lifting eye must not be used.

Before lifting the motor – check that the lifting eye and threaded parts are undamaged. When this is checked, make sure that the lifting eye is tightened.

5 Installation and commissioning

Prior to starting work on the motor, make sure that it is unplugged from the mains.

5.1 General

Check the motor data plate to confirm that cables and overload protections are correctly dimensioned.

5.2 Foundation

The end user is responsible for the foundation where the motor will be mounted.

The foundation will be dimensioned to withstand occurring vibrations and forces.

5.3 Bearings

Before the motor is set up on site, remove bearing protections (if such are provided).

For motors with regreaseable bearings the grease quality shall be checked when the motors have been stored for a period longer than six (6) months. In such case it is best to change the grease using the grease stated in chapters Lubrication interval. It's also possible to use equivalents of these greases. When changing the grease grade the bearings are to be washed with a proper bearing cleaning liquid and dried thoroughly.

5.4 Insulation resistance

Before the motor is set up measure the insulation resistance to frame: The lowest recommended insulation resistance at a winding temperature of approx. 20°C should amount to minimum 20 MΩ for size 56-80, 10 MΩ for size 90-180 and 5 MΩ for size 200-400 (greater than 100 MΩ is recommended before start-up of motor).

The insulation resistance is reduced by 50% for each 10K temperature rise. The resistance is doubling every time the temperature decreased by 10K.

If the measured insulation resistance is lower the motor must be subjected to drying. During the drying process the conditions should be

such that the humidity is removed from the windings i.e. at least the terminal box cover must be removed to facilitate the air exchange within the motor.

If drain plugs are mounted, remove them during the drying process. The drying temperature is recommended 60-80°C and must not exceed 100°C.

After the drying process the insulation resistance will be measured again. Remember to remount the drain plugs.

During and directly after measuring the insulation resistance, harmful voltage is present in the terminals. Therefore it is forbidden to touch them. To neutralize the voltage, it is necessary to ground the frame and each winding grounded to the frame.

5.5 Distance for cooling

Whether free flow of cooling air, necessary for proper operation of the motor, will be provided. Minimal distance between the end of the motors frame (fan cover) and other elements:

- IEC 56 – 71: 12mm
- IEC 80 – 90: 15mm
- IEC 100 – 112: 20mm
- IEC 132 – 225: 40mm
- IEC 250 – 280: 45mm
- IEC 315: 50mm
- IEC 355 – 400: 100mm

5.6 Balancing

The rotor is dynamically balanced. The balancing has been done with a half-key fitted to the shaft, according to IEC 60034-14.

5.7 Mounting of the motor

5.7.1 Coupling drives

Since the rotor is dynamically balanced, the balancing has been done with a half-key fitted to the shaft. This means that, to avoid vibrations, coupling halves and pulleys shall be balanced with a half-key, after the making of the keyway.

The installed motor shaft centre line may show a misalignment of up to 0,1mm with respect to that of the driven machine shaft. As reference the clearance (a) of min. 1mm must be allowed between the coupling halves. For sizes 315-400 the minimum value is 1,5mm. See Figure 1 below.

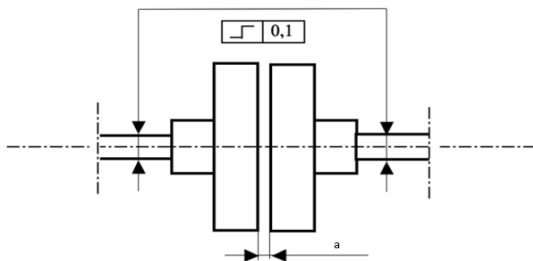


Figure 1. Using coupling on motor shaft.

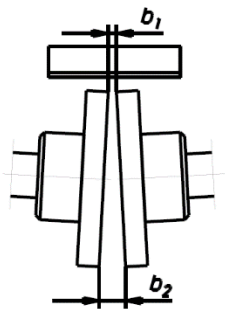


Figure 2 Maximum permissible non-concentricity

$$b = b_2 - b_1 = 0,1\text{mm}/\varnothing 200\text{mm}$$

For further information it is recommended to follow the coupling supplier's instructions.

5.7.2 Belt drives

For belt drives the belts must be tightened according to the supplier of the driven equipment. Care must be taken to ensure that the pulleys are in parallel axes.

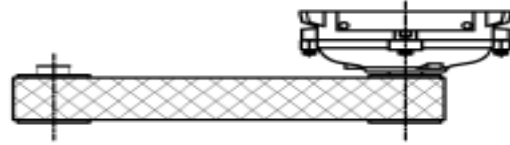


Figure 3 Illustration of belt mounted on shaft

Be certain not to exceed the maximum radial load of the bearing. Otherwise, it may lead to reduced lifetime of bearings and overloading of the shaft.

5.7.3 Drain plugs

Depending on motor size and motor group most of the BEVI motors have drain holes for dewatering the interior of the motor when so is needed. The holes are plugged with a screw or rubber plug and can be removed when needed.

Type Sh, 2SIE, 3SIE, 4SIE, SEMh and 3SSIE has drain holes on sizes 56-80 and 132-315.

Type 3D, 3D2, 3D3 and 3D4 has drain holes from size 250.

All other motors can be ordered with drain holes when required.

5.8 Electrical connection

The motor must be earthed on at least one of the earth terminals on the motor.

In the normal three phase, single speed motor the terminal box contains a terminal board with six terminals, and an earth terminal in the housing. If the motor is equipped with options like thermocontacts, PTC thermistors or heaters, there are extra terminals for this purpose inside the terminal box.

When open the terminal box, loosen every two fixing bolts diagonally by 3-5 threads gradually then remove all the bolts. When fasten the terminal box, fix the bolts with 3-5 threads left, then fasten every two bolts diagonally till all the fixing bolts are fastened.

Or the edge of the terminal cover may crack by stress.

The cable entries – normally metric threads – must at least have the same IP class as the motor. The cable gland will be dimensioned to get a good fit to the cable.
Unused cable gland holes on the terminal box must be sealed to maintain correct IP protection class.

After the motor has been electrically correctly connected with correct cables and cable lugs, tightened the terminal nuts with correct tightening torque according to Table 7, mount the terminal box lid correctly, so the rubber seal will stop water and dust from penetrating the electrical parts inside.

The motor must be installed in accordance with the generally in force principles and regulations by a qualified electrician.

6 Connecting options

6.1 Direct on-line (DOL) start

All BEVI motors are designed to be started – with full nominal load – direct online.

For three phase single speed motors the motor can – depending on voltage supply – be connected Y (star) or D (delta) for correct use of the motor.

For two speed motors, single speed motors or other special motors there are other conditions to consider when connecting the motor. Normally the connection diagram is presented inside the terminal box lid. You can also look in Chapter 10 – Specific motor data – for correct connection diagram.

6.2 Star/Delta (Y/D) start

The Y/D starting method can be used when the supply voltage has the same value as the motor when using D connection.

All connection jumpers on the motor terminal must be removed.

When in need of a low starting current and when

a low starting torque can be accepted (approx. 20-30% of the direct start values) a Y/D-starter can be used as starting method.

At Y/D-start method all connector jumpers on the terminals must be removed to give room for a suitable Y/D-starter. BEVI can provide such switches, www.BEVI.com.

6.3 Output from motor during special ambient situations

The output of motor is based on the operation conditions; ambient -20 °C - + 40 °C, altitude up to 1000m and S1 duty. If the motor operates at different conditions, the following rating factors shall apply:

6.3.1 Ambient temperature

Maximum ambient temperature is +60 °C, with a derating of output above +40 °C as in table:

Ambient temperature [°C]	42,5	45	47,5	50
Output factor	0,98	0,96	0,94	0,93
Ambient temperature [°C]	52,5	55	57,5	60
Output factor	0,91	0,90	0,88	0,86

Table 2 - Derate factor for ambient temperature

Wood drying motors have ambient temperature +90°C and are not included in above table. See Wood drying motors type 3DT, 3DT2, 3DT3, 3DT4 for more information.

6.3.2 Altitude

Maximum altitude above sea level is 4000 m, with a derating of output above +1000 m as in table:

Hight above sea level [m]	1500	2000	2500
Output factor	0,96	0,92	0,88
Hight above sea level [m]	3000	3500	4000
Output factor	0,84	0,80	0,76

Table 3- Derate factor for high altitude

6.3.3 Different supply

Motor wound for 50 Hz can also be supplied with 60 Hz with the following approximated factors:

Rated supply voltage 50 Hz [V]	Voltage 60Hz [V]	Factor for duty with supply with 60Hz and different voltage						
		Speed	Power	Nominal torque	Starting torque	Break down torque	Nominal current	Starting current
230	230	1,20	1,00	0,83	0,69	0,69	1,00	0,83
400	380	1,19	1,00	0,79	0,63	0,63	1,05	0,79
400	400	1,20	1,00	0,83	0,69	0,69	1,00	0,83
400	440	1,20	1,10	0,92	0,84	0,84	1,00	0,92
400	460	1,20	1,15	0,96	0,92	0,92	1,00	0,96
400	480	1,20	1,20	1,00	1,00	1,00	1,00	1,00

Table 4- Factor for supply with 60Hz

6.4 Frequency inverter operation

In general, all BEVI three phase single speed motors can work with frequency inverters. The insulation system in modern electric motors is dimensioned to withstand the peaks from the Inverter.

Permissible output parameters of the frequency inverter (measured on the motor terminals – including supply cable between motor and frequency inverter) is $U_{peak} \leq 1,35kV$ and $t_r \geq 0,8\mu s$.

Normally motor/inverter combination with supply $\leq 480V$ is below this limit. But with supply $>480V$ actions to protect the motors lifetime need to be

consider. As option you can order special wound motors with reinforced insulation of the copper wires. Or use special filter between motor and inverter to limit dU/dt peaks.

Below table is valid with cable length $\leq 150m$. For more information about filters (dU/dt, sinewave and/or common mode filters) actions need to take care of based on longer supply cables, we refer to the manufacturer of frequency inverters and/or filter manufacturer.

What type of inverters and motors to choose depends on motor load, speed control range, ventilation/cooling method.

Nominal supply voltage U_n	Motor power $< 75kW$	Motor power $\geq 75kW$ and $< 350kW$
$U_n \leq 480V$	Standard insulation	Standard insulation with insulated bearing / bearing end shield on ND side
$480V < U_n \leq 600V$	Standard insulation + dU/dt filters OR Reinforced insulation	Standard insulation + dU/dt filters + insulated ND bearing / bearing end shield. OR Reinforced insulation + insulated ND bearing / bearing end shield.
$600 < U_n \leq 690V$	Reinforced insulation AND dU/dt-filters at converter output	Reinforced insulation AND dU/dt-filters at converter output + insulated ND bearing / bearing end shield.

Table 5 Motor selection when using BEVI frequency inverters.

Instead of dU/dt filter sine-wave filter can be used in most cases, check with the supplier of filter and/or frequency inverter.

6.4.1 Motor cooling

Pay attention when running the motor at lower speed without forced cooling (IC 416). As a general rule, speeds below 50% of the nominal speed on the motor during longer periods leads to a high risk of overheating the motor, since the internal motor fan doesn't rotate fast enough to maintain the necessary cooling degree. Depending on ambient temperature, motors with full load and duty point below 25Hz and higher than 70Hz are normally in need of forced cooling.

6.4.2 Thermal protection

For the reason mentioned in chapter 6.3.1 it is highly recommended to equip the motor with thermal protectors (like PTC thermistors or thermocontacts) and connect it to the frequency Inverter.

6.4.3 Bearing currents

For bigger motors from 75kW and up BEVI normally recommends the use of insulated bearing on the NDE (Non-Drive End) of the motor to prevent bearing currents that can occur when controlling the motor with a BEVI frequency inverter. More detailed data can be viewed in *Table 1*. Other brands of frequency inverters supplying the BEVI motor, BEVI gives no recommendations, *Table 1* can only be used as guideline.

6.4.4 EMC and cables

To fulfil the EMC directive, both EMC cable glands and shielded cables must be used the whole way between the Inverter and the motor, also signal cables must be handled the same way. Be assured that the cable shield will be properly grounded in all ends.

7 Checklist at motor start-up

Before putting the motor into service:

- remove all unnecessary objects from the close surroundings of the motor,
- clean the motor and driven object,
- check whether a free cooling air intake to the fan is ensured,
- check the electrical installation, the circuit breaker, measuring instruments and other auxiliary and protection equipment for correct operation,
- check all the fixing screws and cable connections for safe tightening as well as all elements critical for the motor protection grade,
- check the effectiveness of earthing,
- check whether the set is ready for start-up,
- carry out a test run.

During test run of the set, check:

- line voltage,
- current,
- motor rotating in the correct direction,
- effectiveness of motor cooling and correct coupling with driven object,
- whether abnormal vibrations or other malfunctions of the motor are present,
- temperature rises of respective motor elements, such as bearing shields, bearings, frame.
- starting-up equipment elements, control, and protection devices, for correct operation.
- electrical parameters attained by the motor and evaluated the correctness of motor type selection.

After reaching operating temperature, it is recommended to tighten all electrical connections once more. If the motor operates under conditions where vibrations are unavoidable, the electrical connection should be checked regularly and be connected with a cable with multi stranded core. After the above recommended procedures are accomplished and correct operation of the drive motor and driven machine is attained, the motor may be regarded as commissioned after installation.

8 Maintenance

8.1 Service of motor during operation

During motor operation carry out the following routine checks:

- motor for correct operation.
- motor cooling effectiveness.
- bearings for correct operation - no knocks or whistle are permitted, after approximately 10 hours of running after start-up.
- whether any abnormal vibrations are present.
- motor and driven object coupling condition.
- whether the current consumption [A] is within the rated value (nominal current).

The motor must be immediately stopped, when:

- abnormal temperature rise of the motor frame is started.
- fume or smell of burning get out of the motor or installation.
- motor fan is damaged.
- driven object is damaged.
- for any other reason, when starting-up of motor and driven object is hazardous to the environment.

Restart of the motor is permitted only after all stated faults are rectified.

8.2 Periodical inspections

To maintain the full technical efficiency of the motor, all malfunctions stated during motor operation must be solved and corrected immediately.

Apart from the above rule, each motor in operation should be subjected to the following periodical inspection procedures:

1. Minor inspection every 6 month (if the motor operates in a dusty room, every 3 month or even more frequently).
2. Major inspection.

The minor inspection of motor could cover the following procedures:

- external visual inspection and motor cleaning.
- measurement of stator winding insulation resistance performed with a 500 V megger.
- checking of all contacts and fixing screws for safe tightening.
- inspection of supply mains cable and earthing conductors.

When signs of wear are noticed during the minor inspection, the major inspection must be performed. Depending on type of wear found the major inspection could cover the following procedures:

- dismantling of motor.
- removal of rotor.
- inspection of stator with particularly attention to the condition of windings.
- winding insulation resistance measurement.
- inspection of rotor.
- inspection of bearings, exchange of grease in the bearing chambers if necessary. (motors with open bearings).
- inspection of start-up-, protection- and control equipment.

All faults stated during the inspection must be removed and used-up parts must be replaced with new ones. It is recommended to renew the protective coatings.

During major inspection and eventual repair, be sure the technical requirements quoted in the motor rating plate are met.

It is recommended to subject the motor to curtailed tests. Please contact BEVI for further information. BEVI can also assist with the curtailed tests.

8.3 Bearings and lubrication – general

BEVI motors are normally fitted with ball bearings series 62 & 63. Bigger 4-, 6-, 8-pole motors in foot respectively foot/flange execution can be ordered with series NU roller bearings on DE side. For further information, see Chapter 10 Specific motor data.

The values of admitted radial and axial forces of the shaft, which can be obtained from BEVI, have been calculated at the assumption of some

20000-30000 work hours for the bearings, depending on type.

In case of heavy work conditions and at high radial forces acting on the shaft end the ball bearing at the drive (DE) side can be replaced with a roller bearing series NU2 or NU3 of the same dimensions, if the motor is a 4-, 6- or 8-poled horizontally mounted motor.

For vertically mounted motors with high axial loads, angular contact ball bearings type 7xxx is recommended on drive (DE) side.

The wave washer on a standard BEVI motor is normally placed at the NDE side.

Motors with regreaseable bearings are filled with grease - including the bearing chambers - and are ready for operation. However, it is a good idea to give the bearings some more grease during the first run of the motor.

Refilling of bearings with grease should be accomplished during motor operation by means of a grease gun through the grease nipples arranged at the bearing shields. Before refilling the bearings with grease, clean the grease nipples thoroughly.

Regreasing instruction during operation:

- Remove the grease outlet plugs or screws on both Drive End (DE) and Non-Drive End (NDE) side. If necessary – stop the motor and remove the fan cover to reach the grease nipple and grease outlet.
- Clean the grease nipples.
- Inject correct amount of grease into the nipple.
- Let the motor run for 1 hour.
- Clean off the excess grease from the grease outlets and close them with the plugs or screws.

Be aware of rotating parts during regreasing operation!

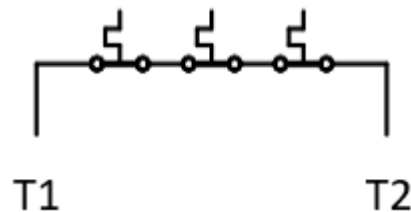
9 Options

9.1 Thermocontacts

Thermocontacts can as an option be mounted into the motor's windings. Normally one thermocontact for each winding. The three thermocontacts are internally connected in serial, so only two wires will be present in the terminal box.

The function for a thermocontact is normally closed (NC), when the temperature of the winding reaches the rated temperature of the thermocontact bimetal, the contact opens and the contactor connected to the motor and thermocontact will cut off the power to the motor.

A normal temperature for the thermocontact is 140°C or 150°C ± 5K.



*Figure 4 Thermocontact connection.
Normally the wires are marked T1-T2
or P1-P2*

9.2 Thermistors (PTC)

Just like the thermocontact the PTC thermistor can be ordered as an option. The PTC thermistor is normally mounted one per winding, internally connected in serial, leading to only two wires appearing in the terminal box.

The PTC thermistor needs to be connected to a thermistor relay, BEVI can supply such material, or when using a frequency inverter, a multifunction contact can be used for controlling the signal from the PTC thermistor.

A normal temperature for the PTC thermistor is 140°C or 150°C.

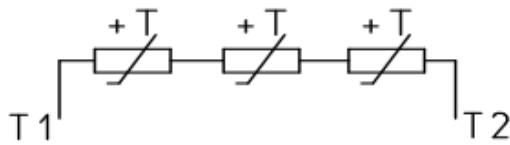


Figure 5 PTC thermistor connection. Normally the wires are marked T1-T2 or P1-P2.

Information about ptc characteristic;

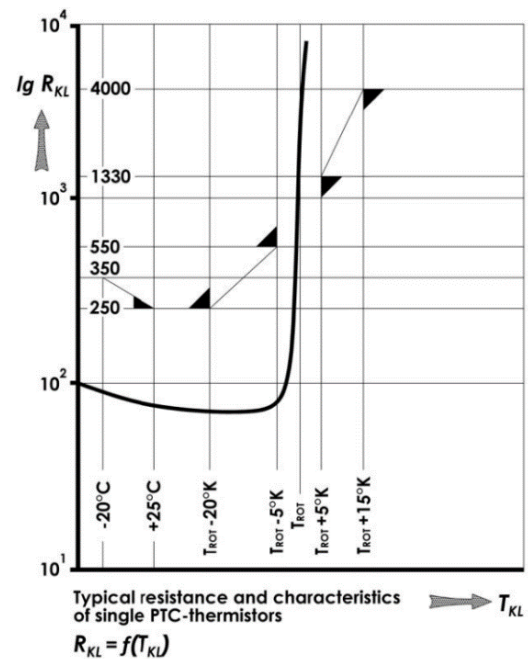


Figure 6 Single Ptc-characteristic

9.3 PT100 sensors

Just like the thermocontact the PT100 can be ordered as an option. The PT100 is normally mounted one per winding. For bigger motors PT100 sensors are mounted near each bearing. Each PT100 sensor cable sets are monitored separately. Normal calibration level for BEVI motors for windings are +140°C and +85°C for bearings.

This kind of Platinum resistive sensors (Pt) is also available as Pt-500 and Pt-1000.

Information about Pt-100 characteristic;

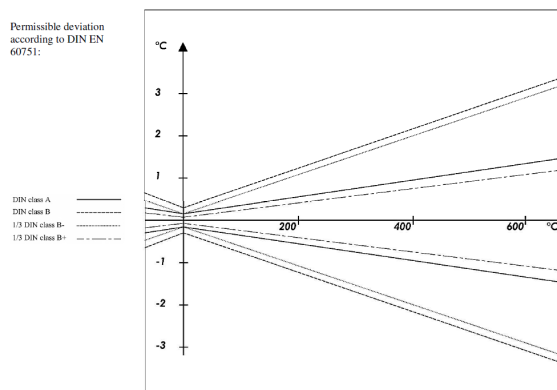


Figure 7 Characteristic for Pt-100

9.4 Forced ventilation (IC416)

Under normal circumstances, the shaft mounted motor fan supplies the electric motor with sufficient airflow to cool the motor down. But when the motor is supplied by a frequency inverter, the motor speed may be too slow to provide sufficient cooling. The solution is to put a forced ventilation at the back of the motor, replacing the shaft-mounted fan.

The motor and forced ventilation shall be connected according to the wiring diagram inside the terminal box. The forced ventilation shall be connected to a fixed frequency power source to work correctly.

There can be a separate terminal box for the forced ventilation, or a separate terminal inside the motor terminal box.

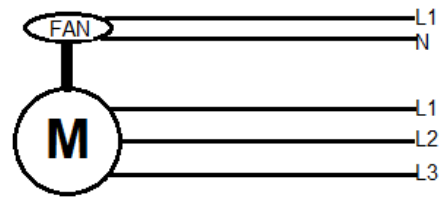


Figure 8 Example of single phase forced cooling connection

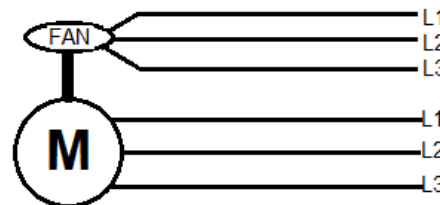


Figure 9 Example of three phase forced cooling connection.

9.5 Anti-condensation heaters

Anti-condensation heaters are used in cases of a risk of condensation inside the motor. This can occur during long-time standstill of a cold motor in humid air, or intermittent duty where the working motor is having long periods of standstill. In this case the temperature variation inside the motor makes the air to condensate.

The anti-condensation heater is used to heat the inside of the motor, to prevent humidity during standstill.

The anti-condensation heaters shall be connected according to the wiring diagram inside the terminal box, separate power supply.

Do not power the heater while the motor is in operation, only when the motor is at standstill.

9.6 Mechanical brake

The mechanical brake is in braking mode at power-off (the motor shaft is locked), when turning the voltage on, the brake releases and the motor shaft is rotating freely.

The motor and DC brake shall be connected according to the wiring diagram inside the terminal box. The DC brake coil shall be connected to a fixed frequency power source to work correctly, for example when the motor is running with a frequency inverter.

The brake torque is correct adjusted at delivery, after a while the air gap for the brake disc may need to be adjusted to work properly.

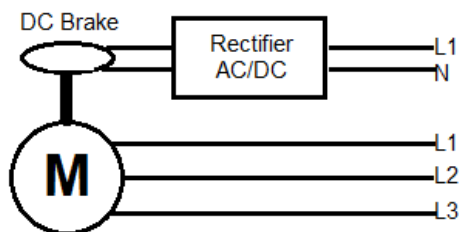


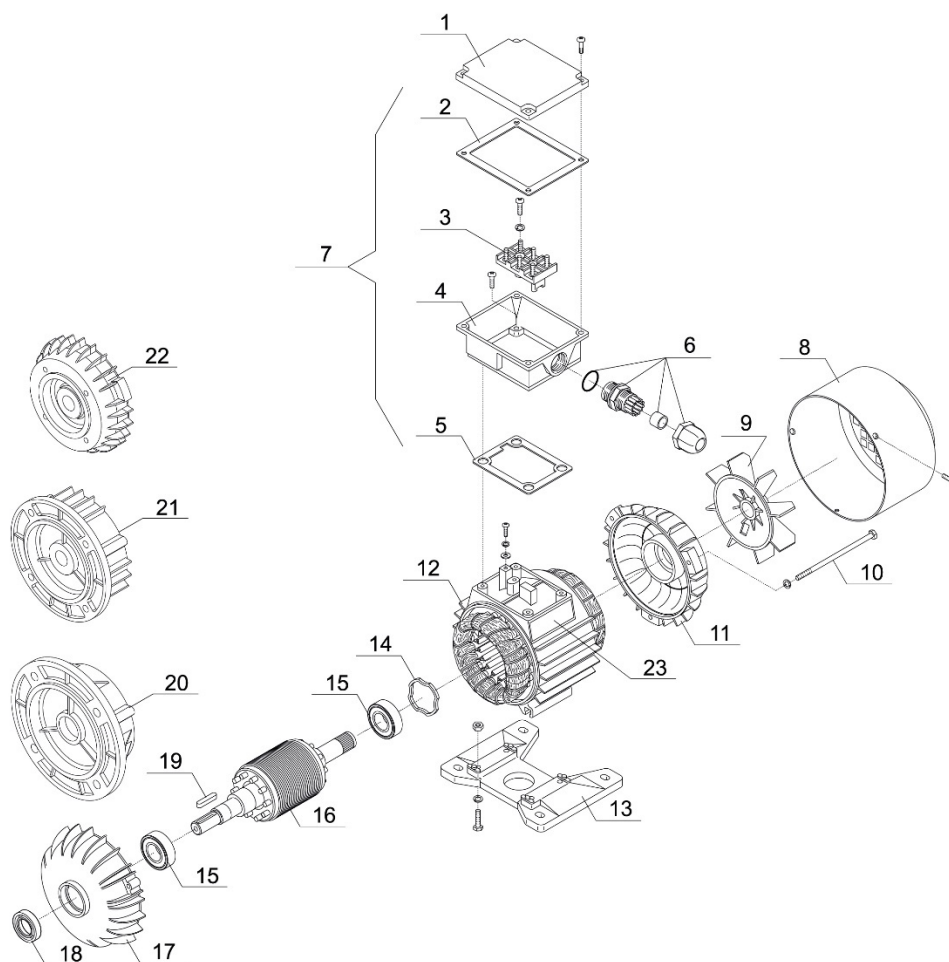
Figure 10 Example of DC brake motor connection

To work safely, the DC brake must always have correct voltage supply.

10 Specific motor data Sh, 2SIE, 3SIE, 4SIE, SEMh, 3SSIE

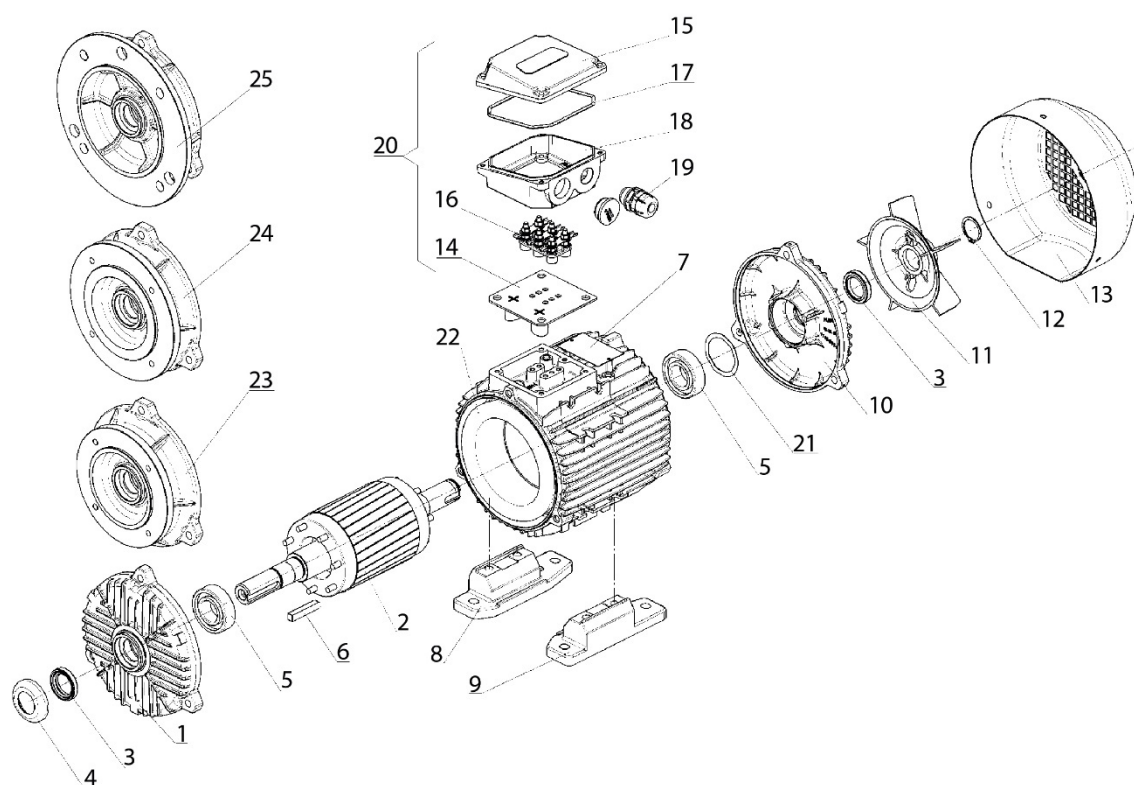
10.1 Exploded views

10.1.1 Size 56-80



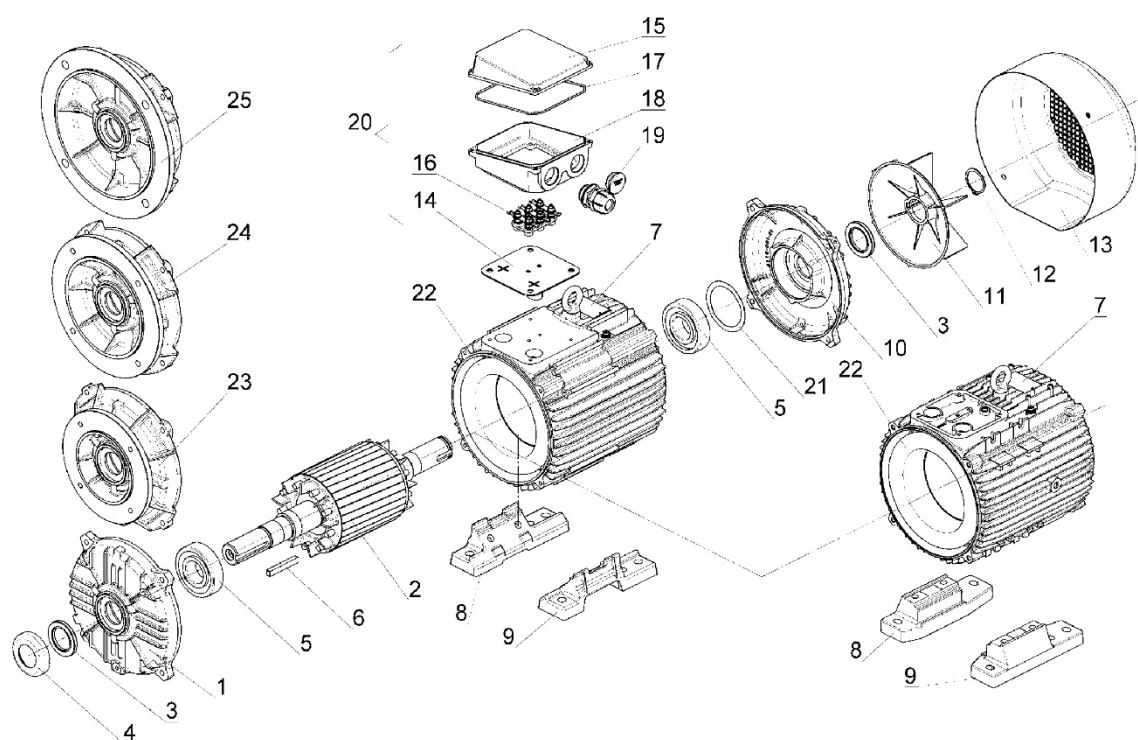
Item	Description	Item	Description	Item	Description
1	Terminal box cover	9	Fan	17	DE shield
2	Rubber gasket	10	Tie rod	18	Shaft seal
3	Terminal board	11	NDE shield	19	Key
4	Terminal box	12	Stator	20	Flange B5
5	Rubber gasket	13	Foot	21	Flange B14/C1
6	Gland	14	Spring washer	22	Flange B14/C2
7	Terminal box complete	15	Bearing	23	Name plate
8	Fan cover	16	Rotor		

10.1.2 Size 90-112



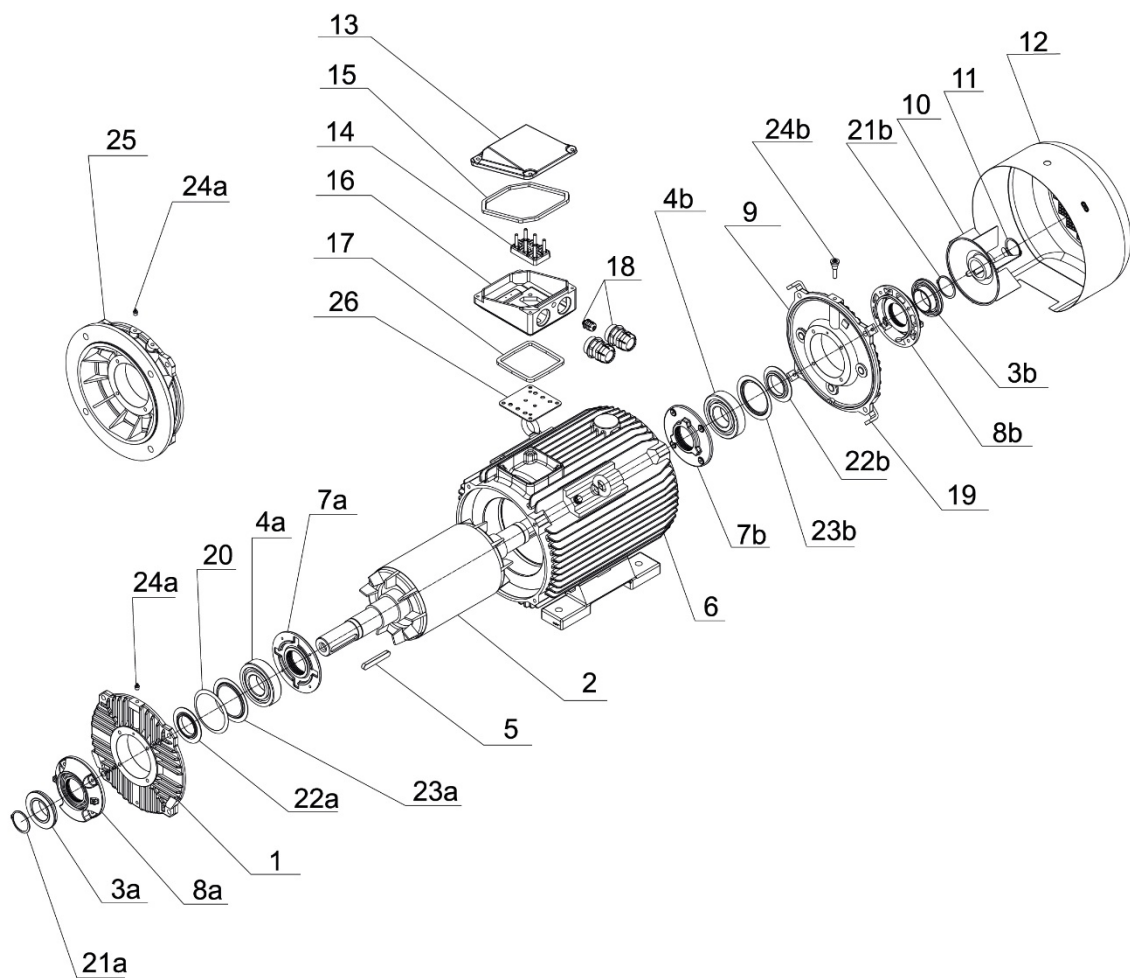
Item	Description	Item	Description	Item	Description
1	DE shield	10	NDE shield	19	Gland
2	Rotor	11	Fan	20	Terminal box complete
3	Shaft seal	12	Seeger ring	21	Spring washer
4	Shaft seal cover	13	Fan cover	22	Stator
5	Bearing	14	Rubber gasket	23	Flange B14/C2
6	Key	15	Terminal box cover	24	Flange B14/C1
7	Name plate	16	Terminal board	25	Flange B5
8	Sx foot	17	Rubber gasket		
9	Dx foot	18	Terminal box		

10.1.3 Size 132-180



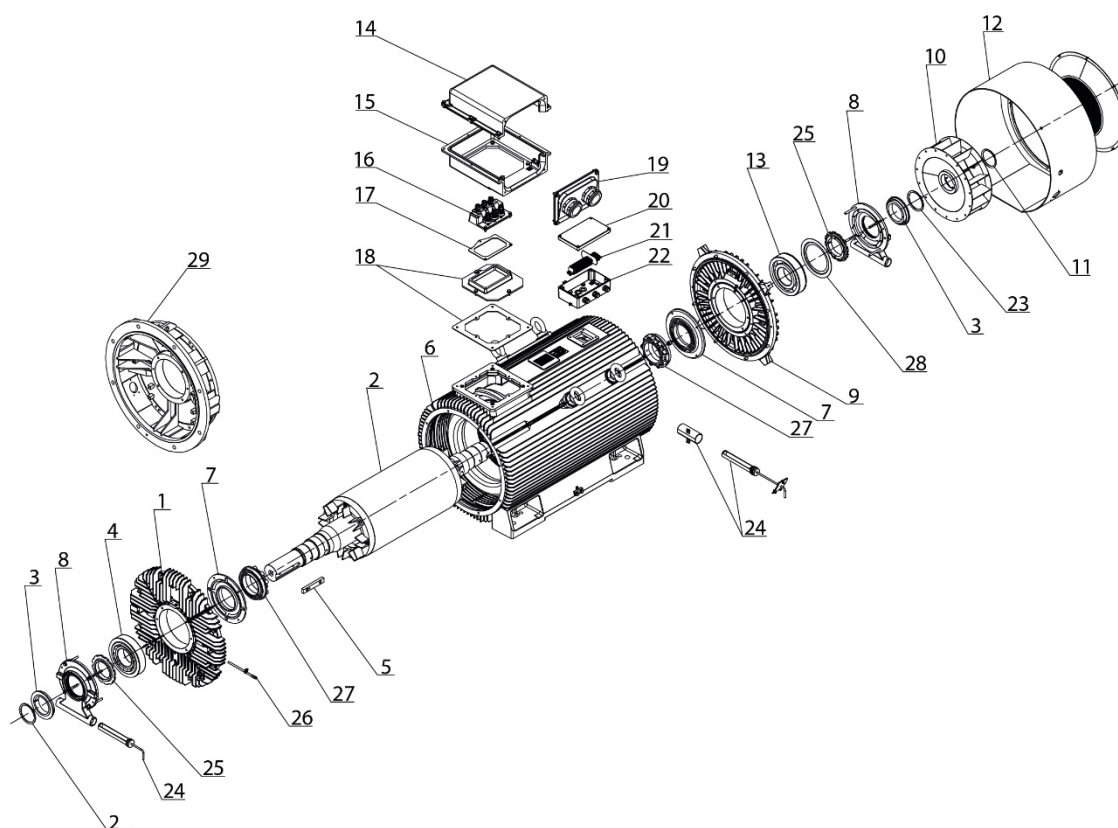
Item	Description	Item	Description	Item	Description
1	DE shield	10	NDE shield	19	Gland
2	Rotor	11	Fan	20	Terminal box complete
3	Shaft seal	12	Seeger ring	21	Spring washer
4	Shaft seal cover	13	Fan cover	22	Stator
5	Bearing	14	Rubber gasket	23	Flange B14/C2
6	Key	15	Terminal box cover	24	Flange B14/C1
7	Name plate	16	Terminal board	25	Flange B5
8	Sx foot	17	Rubber gasket		
9	Dx foot	18	Terminal box		

10.1.4 Size 200-315



Item	Description	Item	Description	Item	Description
1	DE shield	10	Fan	19	Fan cover support
2	Rotor	11	Seeger ring	20	Spring washer
3	Shaft seal	12	Fan cover	21	Seeger ring
4	Bearing	13	Terminal box cover	22	Grease shield
5	Key	14	Terminal board	23	Bearing internal ring
6	Housing with feet	15	Rubber gasket	24	Grease nipple
7	Internal bearing cap	16	Terminal box housing	25	Flange B5
8	External bearing cap	17	Rubber gasket	26	Rubber gasket
9	NDE shield	18	Cable glands		

10.1.5 Size 355



Item	Description	Item	Description	Item	Description
1	DE end shield	11	Fan circlip	21	Terminal strip
2	Rotor	12	Fan cover	22	Auxiliary terminal box housing
3	External labyrinth	13	NDE bearing	23	Circlip of labyrinth
4	DE bearing	14	Terminal box cover	24	Container of used grease
5	Key	15	Terminal box housing	25	Grease retainer
6	Housing with feet	16	Terminal board	26	DE grease conduit
7	Internal bearing cap	17	Rubber gasket	27	Internal labyrinth
8	External bearing cap	18	Intermediate plate	28	Internal ring of NDE bearing
9	NDE end shield	19	Cable glands plate	29	Flange B35
10	Fan	20	Auxiliary terminal box cover		

10.2 Tightening torque

	M4	M5	M6	M8	M10	M12	M16	M18	M20	M22	M24
Electrical connection [Nm]	2	2,5	4	8	12	20	40	-	-	-	-
Max torque for foot mounting [Nm]	-	5	8	22	45	75	91	119	150	184	282

Table 6. Tightening torque for electrical connections and foot mounting.

Cable gland							
	M16	M20	M25	M32	M40	M50	M63
Tightening Torque $\pm 10\%$ [Nm]	3	4	7	11	11	11	13

Table 7 Tightening torque for cable glands

10.3 Construction

Size	56 - 80	90 - 112	132	160 - 315
Stator frame	Aluminium	Aluminium	Aluminium	Cast iron
Flanges (B5, B14)	Aluminium	Cast iron	Cast iron	Cast iron
End shields	Aluminium	Aluminium	Cast iron	Cast iron

Table 8. Sh, 2SIE, 3SIE, 4SIE and SEMh construction materials.

10.4 Bearings

Frame size	Bearing type	Comments
56	6201 2Z	Sealed bearings. Two bearings per motor. No lubrication necessary. Replace when needed.
63	6202 2Z	
71	6203 2Z	
80	6204 2Z	
90	6205 2Z C3	
100	6206 2Z C3	
112	6306 2Z C3	
132	6308 2Z C3	
160	6309 2Z C3	
180 / 180-N	6311 2Z C3	
200-N DE	6312 2Z C3	
200-N NDE	6311 2Z C3	

Table 9. Bearing types for sizes 56-200-N.

Note – Your motor can be equipped with special designed bearings than standard bearings.
Therefore, always check the motor nameplate for correct information regarding your specific motor.

Frame size	Bearing D-end 2-poles	Regrease bearing [gram]	Replace bearing grease [gram]	Bearing ND-end 2-poles	Regrease bearing [gram]	Replace bearing grease [gram]
200	6312 C3	20	100	6312 C3	20	100
225	6313 C3	23	120	6313 C3	23	120
250	6315 C3	30	170	6315 C3	30	170
280	6315 C3	30	170	6315 C3	30	170
315S, MA, MB	6315 C3	30	170	6315 C3	30	170
315MC	6316 C3	35	200	6316 C3	35	200

Table 10. Bearing types and grease amount for sizes 200-315, 2-pole motors.

Frame size	Bearing D-end 4-6-8-poles	Regrease bearing [gram]	Replace bearing grease [gram]	Bearing ND-end 4-6-8- poles	Regrease bearing [gram]	Replace bearing grease [gram]
200	6312 C3	20	100	6312 C3	20	100
225	6313 C3	23	120	6313 C3	23	120
250	6315 C3	30	170	6315 C3	30	170
280	6318 C3	40	260	6318 C3	40	260
315S, MA, MB	6318 C3	40	260	6318 C3	40	260
315 MC, MD	6320 C3	50	300	6318 C3	40	260

Table 11. Bearing types and grease amount for sizes 200-315, 4-6-8-pole motors.

10.5 Lubrication interval

Motor sizes 56-180 + 200-N are equipped with permanently greased bearings and are in no need of regreasing. Motors sizes 200-315 are to be serviced according to *Table 13* below.

Frame size	Regrease or replace	Speed 3600 rpm	Speed 3000 rpm	Speed 1800 rpm	Speed 1500 rpm	Speed 1000-1200 rpm	Speed <1000 rpm
200	Regrease	1100 h	1300 h	1700 h	2000 h	3300 h	3500 h
200	Replace	5500 h	8000 h	14500 h	17500 h	23000 h	25000 h
225	Regrease	1050 h	1250 h	1600 h	1900 h	3000 h	3300 h
225	Replace	5000 h	6500 h	13000 h	16500 h	22000 h	24000 h
250	Regrease	900 h	1100 h	1400 h	1600 h	2700 h	3000 h
250	Replace	4500 h	5000 h	9000 h	11500 h	15000 h	18000 h
280	Regrease	750 h	900 h	1200 h	1500 h	2500 h	2700 h
280	Replace	3750 h	4500 h	6000 h	8000 h	12500 h	15000 h
315	Regrease	750 h	900 h	1200 h	1500 h	2500 h	2500 h
315	Replace	3000 h	4000 h	5900 h	7600 h	11800 h	13000 h

Table 12. Time schedule for regrease/replacement of lubrication.

REMARKS

1. In case of motors operating in temperature above 40°C it's necessary to shorten mentioned above time of operation between regreasing and grease exchange.
2. Periods of regreasing in case of motors operating in vertical position should be shortened by 50% of the above intervals.
3. Your motor can be special designed and have other bearings than standard bearings. Therefore, always check the motor nameplate for correct information regarding your actual motor.
4. Periods of regreasing in case of motors with roller bearings (NU) should be shortened by 50% of the above intervals.
5. Lubrication quality/recommended grease:

Motor type 2Sg

Size 200-280

Renolit H443-HD 88 alt.
SKF LGWA2 or equal

Size 315

Renolit Duraplex EP2 alt.
SKF LGWA2 or equal

Motor type 2SIE/3SIE/4SIE

Size 200-250

Renolit H443-HD 88 alt.
SKF LGWA2 or equal

Size 280-315

Renolit Duraplex EP2 alt.
SKF LGWA2 or equal

Note – Your motor can be equipped with special designed bearings than standard bearings. Therefore, always check the motor nameplate for correct information regarding your specific motor.

10.6 Connection diagrams Sh, 2SIE, 3SIE, 4SIE, SEMh, 3SSIE

10.6.1 Three phase single speed motors

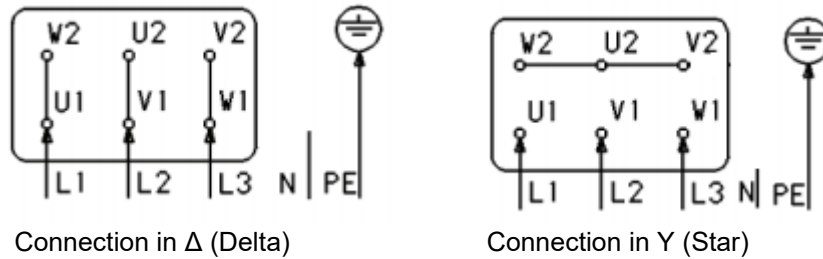


Figure 11 Standard three phase single speed motor

10.6.2 Three phase dual speed motors

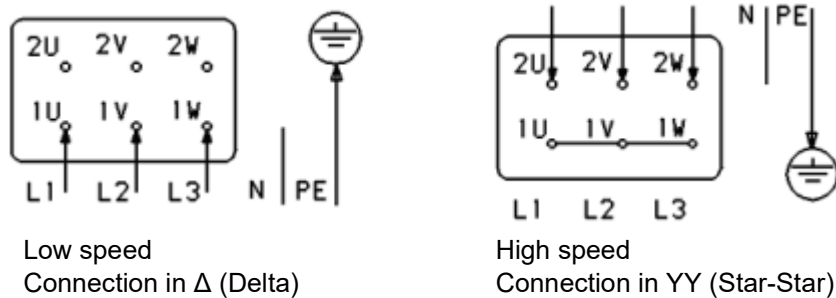


Figure 12 Three phase dual speed motor with single winding (Dahlander), like 4/2-, 8/4-, 12/6-pole

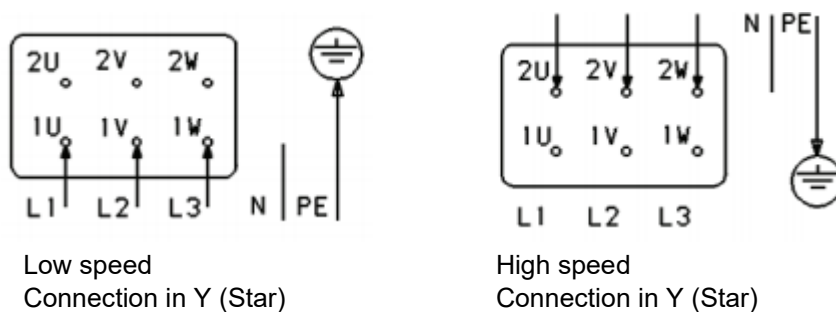


Figure 13 Three phase dual speed motor with separate windings, like 6/4-, 8/6-pole

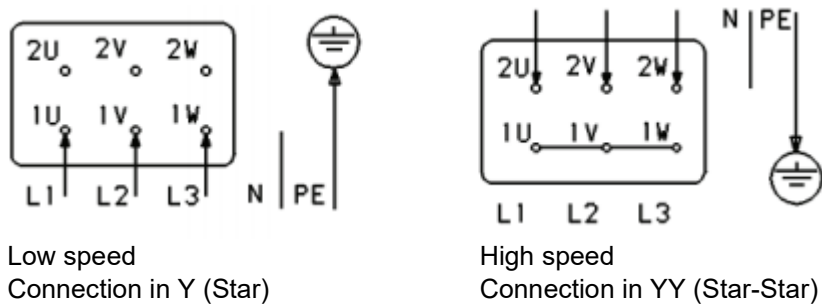


Figure 14 Three phase dual speed motor for ventilation application, with single windings (Dahlander), like 4/2-, 8/4-pole. Motor marked with "W" on the motor data plate.

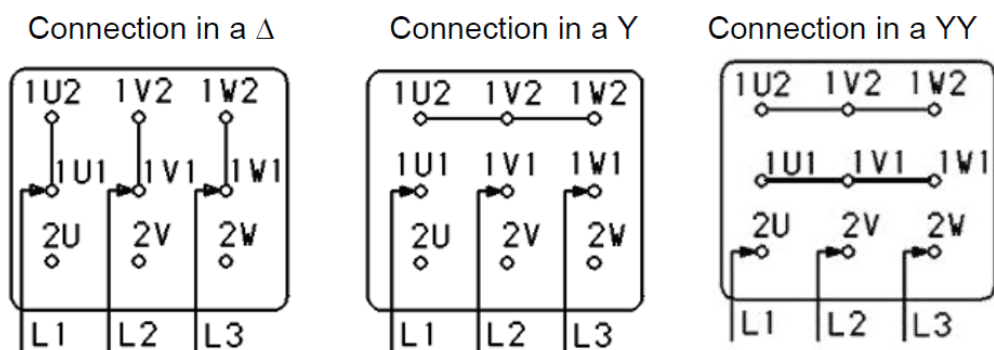


Figure 15 Three phase dual speed motor (nine terminals, for example 4/2-, 8/4-pole).

10.6.3 Single-phase single speed motors

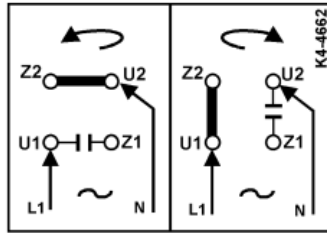


Figure 16 Single phase motor type SEMh/3SSIE, with run capacitor.

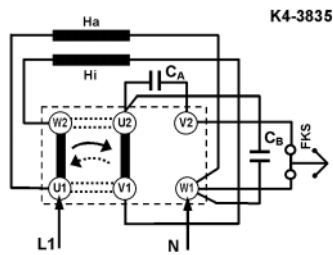


Figure 17 Single phase motor type SEMh-F with Start capacitor CA, run capacitor CB and centrifugal switch.

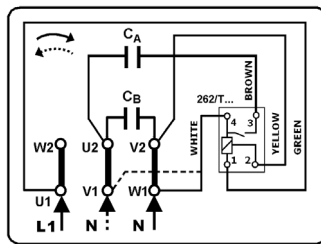


Figure 18 Single phase motor type 3SSIE with Start capacitor CA, run capacitor CB and centrifugal switch.

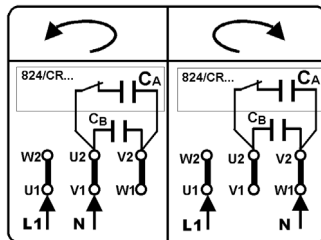
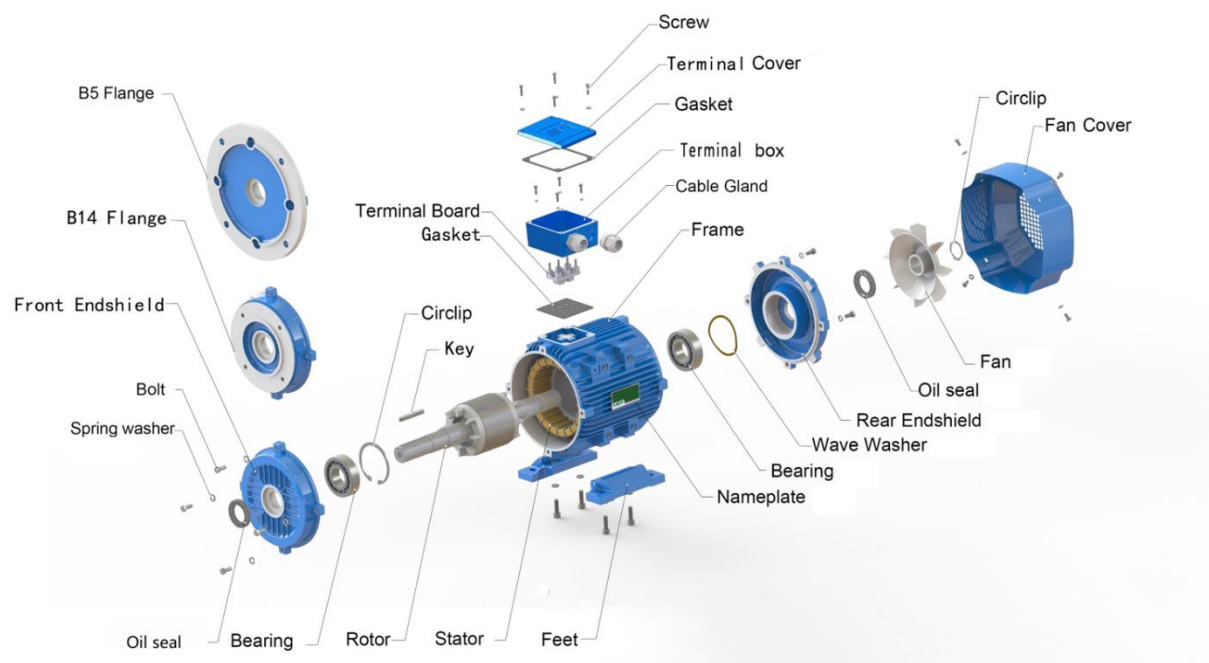


Figure 19 Single phase motor type 3SSIE with Start capacitor CA, run capacitor CB and integrated electrical switch.

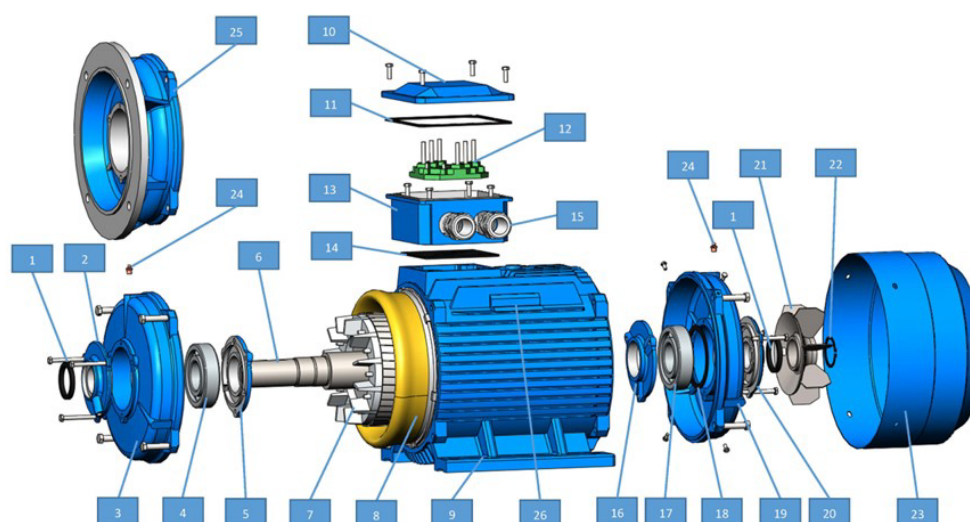
11 Specific motor data 4A, 4A2, 4A3, 4A4, 4D, 4D2, 4D3, 4D4

11.1 Exploded views

11.1.1 Typical exploded view of motors with sealed bearings



11.1.2 Typical exploded view of motors with regreaseable bearings



Name of Parts	Name of Parts	Name of Parts
1 - Shaft seal	10 - Terminal lid	19 - Endshield at NDE
2 - Outer bearing cap at DE	11 - Gasket btw terminal lid and box	20 - Outer bearing cap at NDE
3 - Endshield at DE	12 - Terminal board	21 - Fan
4 - Bearing	13 - Terminal bracket	22 - Circlip
5 - Inner bearing cap at DE	14 - Gasket btw terminal bracket and frame	23 - Fan cowl
6 - Shaft	15 - Cable gland	24 - Grease nipple
7 - Rotor	16 - Inner bearing cap at NDE	25 - Flange endshield
8 - Stator	17 - Bearing	26 - Nameplate base
9 - Enclosure	18 - Spring washer	

11.2 Tightening torque

	M4	M5	M6	M8	M10	M12	M16	M18	M20	M22	M24
Electrical connection [Nm]	2	2,5	4	8	12	20	40	-	-	-	-
Max torque for foot mounting [Nm]	-	5	8	22	45	75	91	119	150	184	282

Table 13. Tightening torque for electrical connections and foot mounting.

Cable gland							
	M16	M20	M25	M32	M40	M50	M63
Tightening Torque $\pm 10\%$ [Nm]	3	4	7	11	11	11	13

Table 14 Tightening torque for cable glands

11.3 Construction

Type	4A, 4A2, 4A3, 4A4		4D, 4D2, 4D3, 4D4
Size	56-132	160-180	80-355
Stator frame	Aluminium	Aluminium	Cast iron
End shields	Aluminium	Aluminium	Cast iron
Flange	Aluminium	Cast iron	Cast iron

Table 15. 4A, 4A2, 4A3, 4A4, 4D, 4D2, 4D3 and 4D4 motors construction materials

11.4 Bearings 4A, 4A2, 4A3, 4A4, 4D, 4D2, 4D3, 4D4

Frame size	Bearing type	Comments
56	6201 2RS C3	Sealed bearings. Two bearings per motor. No lubrication necessary. Exchange when needed.
63	6202 2RS C3	
71	6202 2RS C3	
80	6204 2RS C3	
90	6205 2RS C3	
100	6206 2RS C3	
112	6306 2RS C3	
132	6308 2RS C3	
160	6309 2RS C3	

Table 16. Bearing types for sizes 56-160 for 4A, 4A2, 4A3, 4A4, 4D, 4D2, 4D3, 4D4 motors.

Frame size	Bearing D-end 2-poles	Bearing ND-end 2-poles	Bearing D-end 4-6-8-poles	Bearing ND-end 4-6-8-poles
180	6311 C3	6311 C3	6311 C3	6311 C3
200	6312 C3	6312 C3	6312 C3	6312 C3
225	6313 C3	6313 C3	6313 C3	6313 C3
250	6314 C3	6314 C3	6314 C3	6314 C3
280	6314 C3	6314 C3	6317 C3	6317 C3
315	6317 C3	6317 C3	NU 319 C3	6319 C3
355	6319 C3	6319 C3	NU 322 C3	6322 C3

Table 17. Bearing types for sizes 180-355 for 4D, 4D2, 4D3, 4D4 motors.

Note – Your motor can be equipped with special designed bearings than standard bearings.
Therefore, always check the motor nameplate for correct information regarding your specific motor.

11.5 Lubrication interval

Frame size	Regrease bearing [gram]	3600 rpm	3000 rpm	1800 rpm	1500 rpm	1200 rpm	1000 rpm	500-900 rpm
112	15	4200	4800	7000	7800	8500	10000	10500
132	15	4200	4800	7000	7800	8500	10000	10500
160	20	3200	4200	6000	7000	8000	9000	10000
180	20	3200	4200	6000	7000	8000	9000	10000
200	25	1800	3100	5500	6500	7500	8500	9500
225	25	1800	3100	5500	6500	7500	8500	9500
250	35	800	2000	5000	6000	7000	8000	9000
280	35	800	2000	5000	6000	7000	8000	9000
315	50	800	2000	4600	5500	6500	7500	8000
355	60	400	1000	4000	5000	6000	7000	8000
400	60		1000	4000	5000	6000	7000	8000

Table 18. Lubrication intervals in duty hours [h].

REMARKS

1. In case of motors operating in temperature above 40°C it's necessary to shorten mentioned above time of operation between regreasing and grease exchange.
2. Periods of regreasing in case of motors operating in vertical position should be shortened by 50% of the above intervals.
3. Your motor can be special designed and have other bearings than standard bearings. Therefore, always check the motor nameplate for correct information regarding your actual motor.
4. Periods of regreasing in case of motors with roller bearings (NU) should be shortened by 50% of the above intervals.
5. Lubrication quality/recommended grease:

Recommended grease: Shell Gadus S1 V220 2 or equal.

Mixing different greases is not recommended, as not all greases are compatible with each other.

Do not mix different grease types. Some greases may lose their grease capabilities when mixed.

11.6 Connection diagrams 4A, 4A2, 4A3, 4A4, 4D, 4D2, 4D3, 4D4

11.6.1 Three phase single speed motors

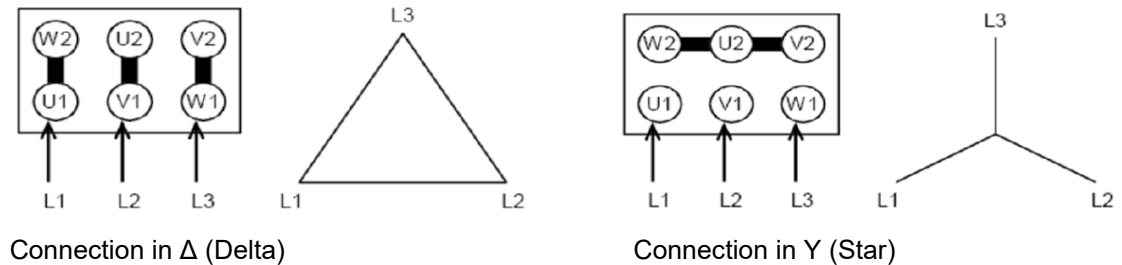


Figure 20 Standard three phase single speed motor

11.6.2 Single phase single speed motors

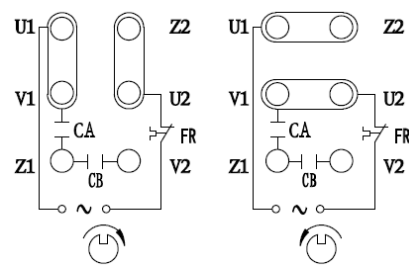


Figure 21 Single phase motor type GMYL with Start capacitor CS, run capacitor CA and FR protector

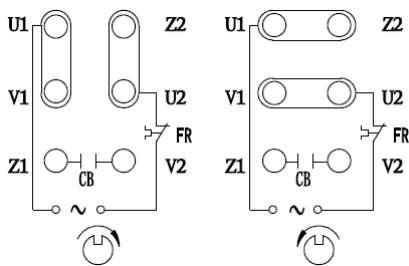


Figure 22 Single phase motor type GMYC with start capacitor CB and FR protector

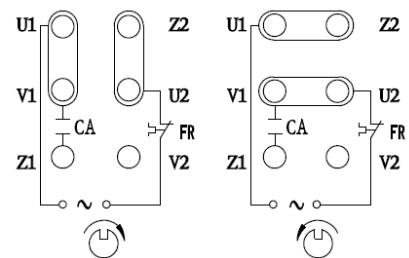
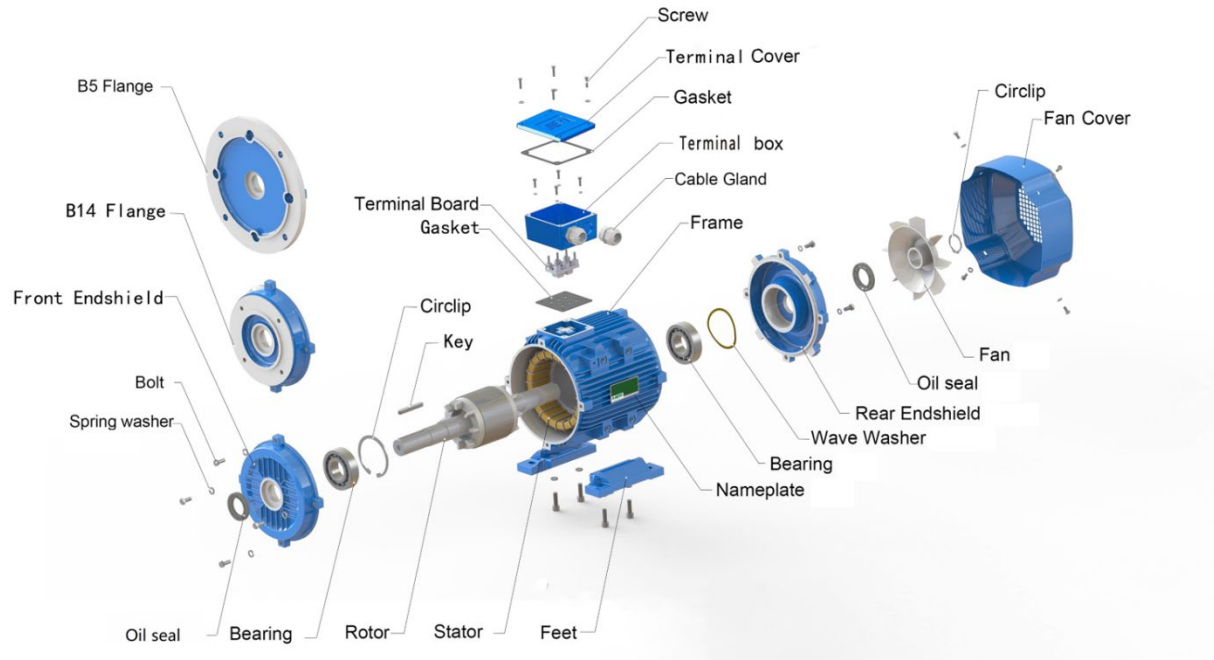


Figure 23 Single phase motor type GMY Y with run capacitor CA and FR protector

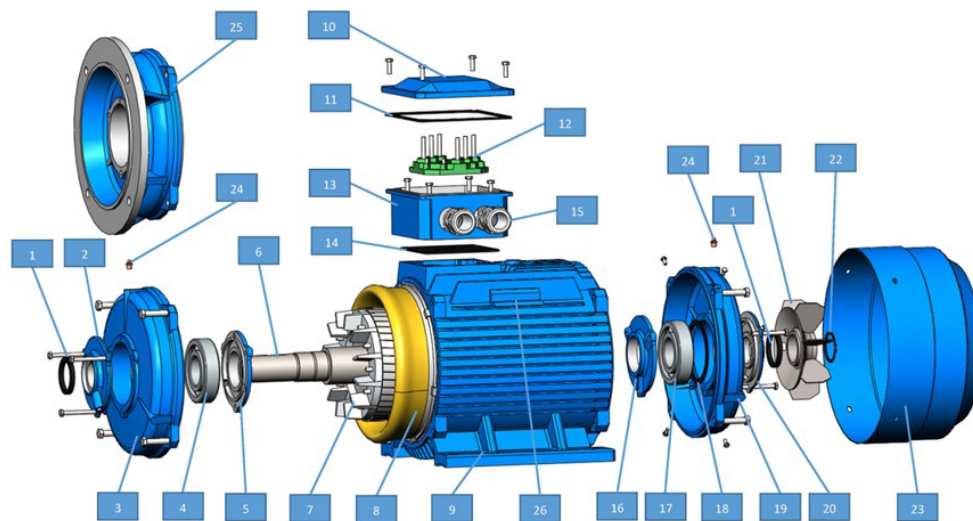
12 Specific motor data 3D, 3D2, 3D3, 3D4, 3D5

12.1 Exploded views

12.1.1 Typical exploded view of motors with sealed bearings



12.1.2 Typical exploded view of motors with regreaseable bearings



Name of Parts	Name of Parts	Name of Parts
1 - Shaft seal	10 - Terminal lid	19 - Endshield at NDE
2 - Outer bearing cap at DE	11 - Gasket btw terminal lid and box	20 - Outer bearing cap at NDE
3 - Endshield at DE	12 - Terminal board	21 - Fan
4 - Bearing	13 - Terminal bracket	22 - Circlip
5 - Inner bearing cap at DE	14 - Gasket btw terminal bracket and frame	23 - Fan cowl
6 - Shaft	15 - Cable gland	24 - Grease nipple
7 - Rotor	16 - Inner bearing cap at NDE	25 - Flange endshield
8 - Stator	17 - Bearing	26 - Nameplate base
9 - Enclosure	18 - Spring washer	

12.2 Tightening torque

	M4	M5	M6	M8	M10	M12	M16	M18	M20	M22	M24
Electrical connection [Nm]	2	2,5	4	8	12	20	40	-	-	-	-
Max torque for foot mounting [Nm]	-	5	8	22	45	75	91	119	150	184	282

Table 19. Tightening torque for electrical connections and foot mounting.

Cable gland							
	M16	M20	M25	M32	M40	M50	M63
Tightening Torque $\pm 10\%$ [Nm]	3	4	7	11	11	11	13

Table 20 Tightening torque for cable glands

12.3 Construction

Size	80-400
Stator frame	Cast iron
End shields	Cast iron

Table 21. 3D, 3D2, 3D3, 3D4 and 3D5 motors construction materials.

12.4 Bearings 3D, 3D2, 3D3, 3D4, 3D5

Frame size	Bearing type	Comments
80	6204 2RS C3	Sealed bearings. Two bearings per motor. No lubrication necessary. Replace when needed.
90	6205 2RS C3	
100	6206 2RS C3	
112	6206 2RS C3	
132	6208 2RS C3	

Table 22. Bearing types for sizes 80-132 for 3D, 3D2, 3D3, 3D4 and 3D5 motors.

Frame size	Bearing D-end 2-poles	Bearing ND-end 2-poles	Bearing D-end 4-6-8-poles	Bearing ND-end 4-6-8-poles
160	6309 C3	6309 C3	6309 C3	6309 C3
180	6311 C3	6311 C3	6311 C3	6311 C3
200	6312 C3	6312 C3	6312 C3	6312 C3
225	6312 C3	6312 C3	6313 C3	6313 C3
250	6314 C3	6314 C3	6314 C3	6314 C3
280	6316 C3	6316 C3	6316 C3 ²	6316 C3
315	6316 C3	6316 C3	6319 C3	6319 C3
355	6319 C3	6319 C3	6322 C3	6319 C3
400	6319 C3	6319 C3	NU326 ECM C3	6326 C3
450	6322 C3	6322 C3	6328 C3	6328 C3

Table 23. Bearing types for sizes 160-400 for 3D, 3D2, 3D3, 3D4 and 3D5 motors.

Note – Your motor can be equipped with special designed bearings than standard bearings.
Therefore, always check the motor nameplate for correct information regarding your specific motor.

Frame size	Bearing D-end 2-poles	Bearing ND-end 2-poles	Bearing D-end 4-6-8-poles	Bearing ND-end 4-6-8-poles
160	7309BEP	6309 C3	7309BEP	6309 C3
180	7311BEP	6311 C3	7311BEP	6311 C3
200	7312BEP	6312 C3	7312BEP	6312 C3
225	7312BEP	6312 C3	7313BEP	6313 C3
250	7314BEP	6314 C3	7314BEP	6314 C3
280	7316BEP	6316 C3	7316BEP	6316 C3
315	7316BEP	6316 C3	7319BEP	6319 C3
355	7319BEP	6319 C3	7322BEP	6319 C3
400	7319BEP	6319 C3	2×7226BCBM	NU226 ECJ C3
450	7322 BCBM	6322 C3	2×7228BCBM	6328 C3

Table 24. 3D, 3D2, 3D3, 3D4 and 3D5 sizes 160-400 motors with heavy axial load in V1 vertical mounting position can as **option** be ordered with angular contact ball bearings.

Note – Your motor can be equipped with special designed bearings than standard bearings.
Therefore, always check the motor nameplate for correct information regarding your specific motor.

² When insulated bearings are used on 280-size 4-, 6- and 8-pole motors, DE-side will have 6317 C3 and NDE-side will have 6317 C3 VL0241.

12.5 Lubrication interval

Frame size	Regrease bearing [gram]	3600 rpm	3000 rpm	1800 rpm	1500 rpm	1200 rpm	1000 rpm	500-900 rpm
112	15	4200	4800	7000	7800	8500	10000	10500
132	15	4200	4800	7000	7800	8500	10000	10500
160	20	3200	4200	6000	7000	8000	9000	10000
180	20	3200	4200	6000	7000	8000	9000	10000
200	25	1800	3100	5500	6500	7500	8500	9500
225	25	1800	3100	5500	6500	7500	8500	9500
250	35	800	2000	5000	6000	7000	8000	9000
280	35	800	2000	5000	6000	7000	8000	9000
315	50	800	2000	4600	5500	6500	7500	8000
355	60	400	1000	4000	5000	6000	7000	8000
400	60		1000	4000	5000	6000	7000	8000

Table 25. Lubrication intervals in duty hours [h].

REMARKS

1. In case of motors operating in temperature above 40°C it's necessary to shorten mentioned above time of operation between regreasing and grease exchange.
2. Periods of regreasing in case of motors operating in vertical position should be shortened by 50% of the above intervals.
3. Your motor can be special designed and have other bearings than standard bearings. Therefore, always check the motor nameplate for correct information regarding your actual motor.
4. Periods of regreasing in case of motors with roller bearings (NU) should be shortened by 50% of the above intervals.
5. Lubrication quality/recommended grease:

Recommended grease: Mobil UNIREX N2, SKF LGWA2 or equal.

Mixing different greases is not recommended, as not all greases are compatible with each other.

Do not mix different grease types. Some greases may lose their grease capabilities when mixed.

12.6 Connection diagrams 3D, 3D2, 3D3, 3D4

12.6.1 Three phase single speed motors

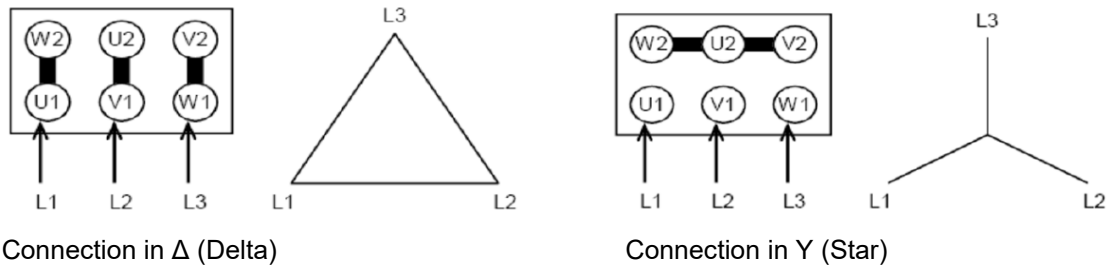


Figure 24 Standard three phase single speed motor.

12.6.2 Three phase dual speed motors

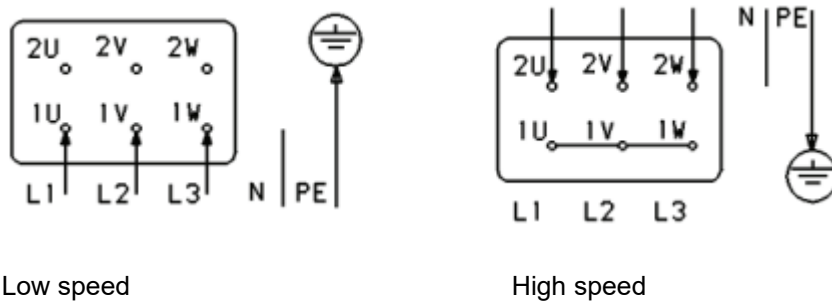


Figure 25 Three phase dual speed motor with single winding (Dahlander), like 4/2-, 8/4-, 12/6-pole.

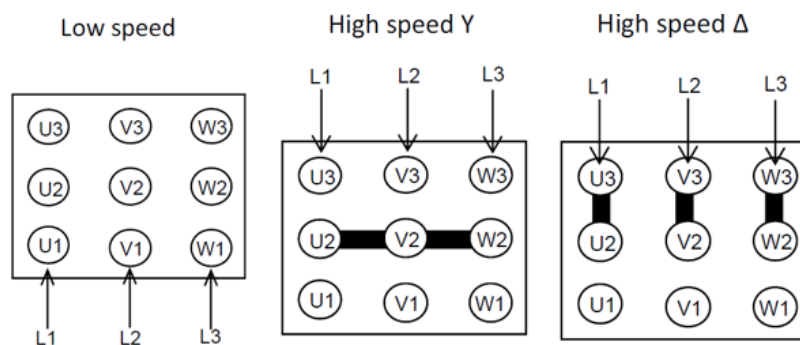


Figure 26 Three phase dual speed motor with separate windings, like 4/6-pole.

13 Wood drying motors type 3DT, 3DT2, 3DT3, 3DT4

13.1 Specific features for motors type 3DT, 3DT2, 3DT3, 3DT4

Cooling

As standard, the wood drying motors are delivered without a shaft mounted cooling fan (standard designation IC418). The motor is cooled by the air flow from the shaft mounted fan (supplied by the customer). Other cooling methods can be supplied, for example a NDE shaft mounted fan and fan cowl (IC411).

Insulation

These motors are delivered with insulation class H as standard.

Others

Fasteners and motor plate are in stainless steel.

13.2 Construction

Size	90-250
Stator frame	Cast iron
End shields	Cast iron

Table 26. 3DT, 3DT2, 3DT3, 3DT4 motors construction materials.

13.3 Bearings 3DT, 3DT2, 3DT3, 3DT4

Frame size	Bearing type	Comments
90	6205 2Z C3	Sealed bearings. Two bearings per motor. No lubrication necessary. Replace when needed.
100	6206 2Z C3	
112	6206 2Z C3	
132	6208 2Z C3	

Table 27. Bearing types for sizes 90-132 for 3DT, 3DT2, 3DT3, 3DT4 motors.

Frame size	Bearing D-end	Bearing ND-end
160	6309 C3	6309 C3
180	6311 C3	6311 C3
200	6312 C3	6312 C3
225	6313 C3	6313 C3
250	6314 C3	6314 C3

Table 28. Bearing types for sizes 160-250 for 3DT, 3DT2, 3DT3, 3DT4 motors.

Note – Your motor can be equipped with special designed bearings than standard bearings. Therefore, always check the motor nameplate for correct information regarding your specific motor.

13.4 Connection diagrams 3DT, 3DT2, 3DT3, 3DT4

13.4.1 Three phase single speed motors

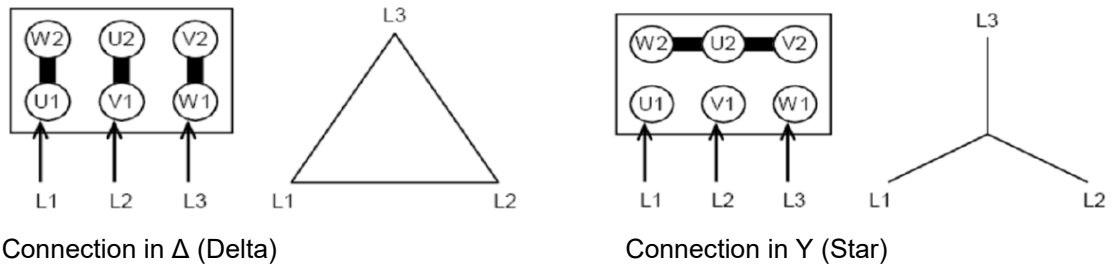


Figure 27 Standard three phase single speed motor.

13.4.2 Three phase dual speed motors

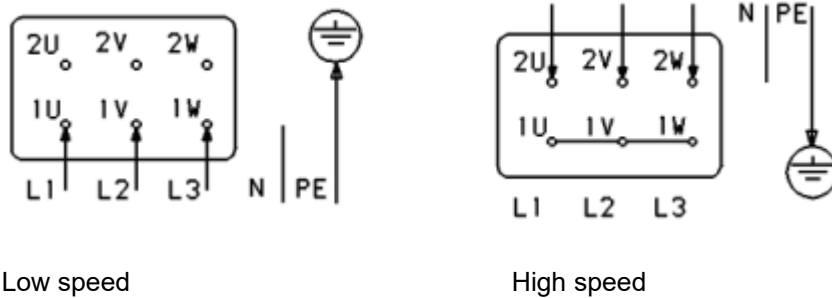


Figure 28 Three phase dual speed motor with single winding (Dahlander), like 4/2-, 8/4-, 12/6-pole.

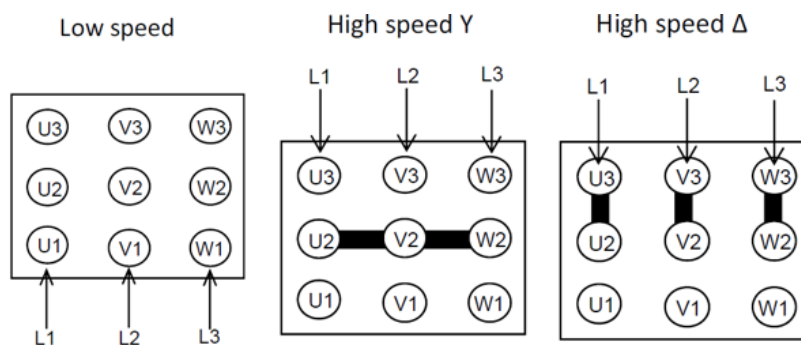


Figure 29 Three phase dual speed motor with separate windings, like 4/6-pole.

13.5 Lubrication interval

The BEVI wood drying motors must be regreased:

- At an environmental drying temperature of +90°C every 600 duty hours, or every 60 day.
- At an environmental drying temperature of +75°C every 1000 duty hours, or every 60 day.

Frame size	Regrease bearing [gram]
90	4
100	5
112	10
132	16
160	20
180	20
200	25
225	25
250	35

Table 29. Lubrication intervals in duty hours [h].

Note that frame size 90 – 132 are normally equipped with sealed bearings and that they are not regreaseable.

After 8000 working hours the motor's bearing grease must be fully replaced. Dismantle the motor and clean all the bearing parts thoroughly. After the cleaning is ready, a new coat of grease can be applied.

REMARKS

1. Periods of regreasing in case of motors operating in vertical position should be shortened by 50% of the above intervals.
2. Your motor can be special designed and have other bearings than standard bearings. Therefore, always check the motor nameplate for correct information regarding your actual motor.
3. Periods of regreasing in case of motors with roller bearings (NU) should be shortened by 50% of the above intervals.
4. Lubrication quality/recommended grease:

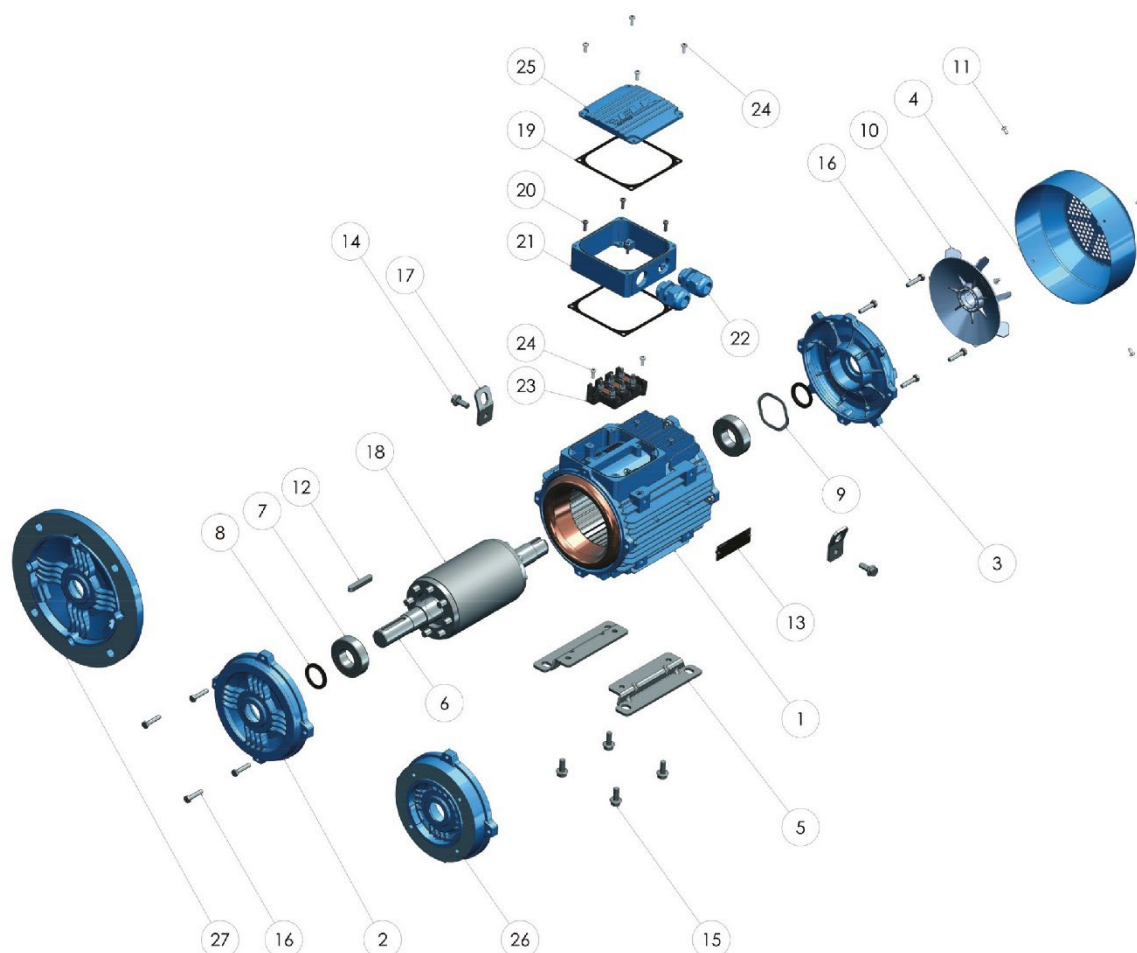
Recommended grease: Renolit Uniway LiX 815 Pa HP or equal.

Mixing different greases is not recommended, as not all greases are compatible with each other

Do not mix different grease types. Some greases may lose their grease capabilities when mixed.

14 Specific motor data 2EL, 3EL, 4EL, 3EC, 2EG, 3EG, 4EG

14.1 Exploded view



Item	Description	Item	Description	Item	Description
1	Housing	10	Fan	19	Terminal box gasket
2	End shield (DE)	11	Screw	20	Screw
3	End shield (NDE)	12	Key	21	Terminal box
4	Fan cover	13	Nameplate	22	Cable gland
5	Mounting foot	14	Screw	23	Terminal
6	Shaft	15	Screw	24	Screw
7	Bearing	16	Bolt	25	Terminal box cover
8	Shaft sealing	17	Lifting lug	26	Flange B14
9	Spring washer	18	Squirrel cage rotor	27	Flange B5

14.2 Construction

Size	56 – 112 (EL)	132 – 180	200 – 315 (EG)
Stator frame	Aluminium	Aluminium (EL) Cast iron (EG)	Cast iron
Flanges (B5, B14)	Aluminium	Aluminium (EL) Cast iron (EG)	Cast iron
End shields	Aluminium	Aluminium (EL) Cast iron (EG)	Cast iron

Table 30. 2 EL, 3EL, 4EL, 3EC, 2EG, 3EG, 4EG

14.3 Bearings

Frame size	Bearing type	Comments
63	6201 2Z	Sealed bearings. Two bearings per motor. No lubrication necessary. Replace when needed.
71	6202 2Z	
80	6204 2Z	
90	6205 2Z	
100	6206 2Z	
112	6206 2Z	
132	6208 2Z	
160	6309 2Z	
180	6310 2Z	
200	6312 2Z	
225	6313 2Z	
250	6315 2Z	

Table 31. Bearing types for sizes 63-250.

Frame size	Bearing D-end 2-poles	Regrease bearing [gram]	Replace bearing grease [gram]	Bearing ND-end 2-poles	Regrease bearing [gram]	Replace bearing grease [gram]
280	6315	30	170	6315	30	170
315	6316	33	170	6315	33	170

Table 32. Bearing types and grease amount for sizes 280-315, 2-pole motors.

Frame size	Bearing D-end 4-6-8-poles	Regrease bearing [gram]	Replace bearing grease [gram]	Bearing ND-end 4-6-8-poles	Regrease bearing [gram]	Replace bearing grease [gram]
280	6317	38	260	6317	38	260
315	6319	45	260	6319	45	260

Table 33. Bearing types and grease amount for sizes 280-315, 4-6-8-pole motors.

Note – Your motor can be equipped with special designed bearings than standard bearings. Therefore, always check the motor nameplate for correct information regarding your specific motor.

14.4 Lubrication interval

Motor sizes 56-250 are equipped with permanently greased bearings and are in no need of regreasing. Motors sizes 280-315 are to be serviced according to lubrication table

Frame size	Pole	DE	NDE
280	2-pole	3200 h	3200 h
280	4-pole	3750 h	4500 h
280	6-pole	9000 h	11000 h
315	2-pole	2900 h	2900 h
315	4-pole	6400 h	6900 h
315	6-pole	9700 h	10400 h

Table 34. Time schedule for regrease/replacement of lubrication.

Recommended grease: Mobil Polyrex EM or equal.

Mixing different greases is not recommended, as not all greases are compatible with each other.

REMARKS

1. In case of motors operating in temperature above 40°C it's necessary to shorten mentioned above time of operation between regreasing and grease exchange.
2. Periods of regreasing in case of motors operating in vertical position should be shortened by 50% of the above intervals.
3. Periods of regreasing in case of motors with roller bearings (NU) should be shortened by 50% of the above intervals.

14.5 Connection diagrams 2EL, 3EL, 4EL, 3EC, 2EG, 3EG, 4EG

14.5.1 Three phase single speed motors

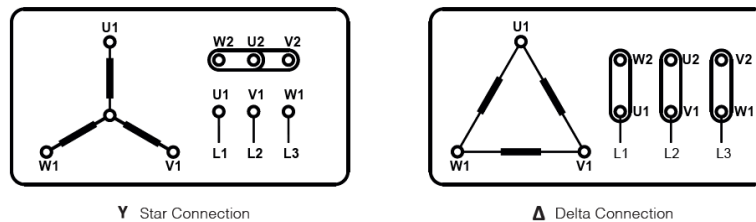


Figure 30 Standard three phase single speed motor

14.5.2 Single phase single speed motors

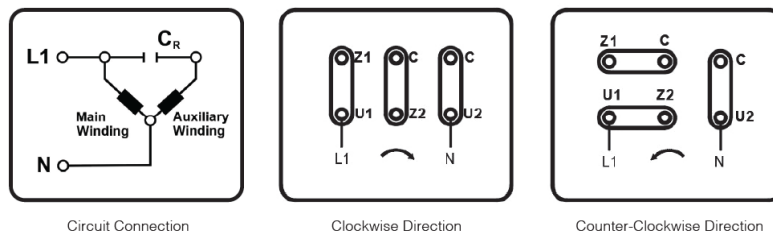


Figure 31 Standard single phase single speed motor

15 Troubleshooting

Electrical failure	Cause	Solution
1 - Motor fails to start	1) Power supply is not switched on.	1) Check switch, fuses, contactors and motor cable lugs.
	2) Stator winding is broken.	2) Leave the motor to a skilled and certified service partner who will heat the broken part to the permissible insulation temperature to soften the varnish, pick up the disconnected wires and weld them. Then wrap the coils, varnish them and make them dry.
	3) Either winding earthed or short circuit between phases.	3) Leave the motor to skilled and certified service partner who will use the same method as 2) and make the earthed or short circuit portion insulated then varnish and dry the part.
	4) Connection mistakes in stator winding.	4) Leave the motor to skilled and certified service partner who will check connection diagram, heat the end turns and reconnect them correctly, then wrap, insulate and varnish them.
	5) Fuse burnt out.	5) Troubleshoot and find out the cause. Replace the fuse with a new one.
	6) Wrong connection in the control device.	6) Check and correct the wiring connection.
2 - Fuse burnt after motor energized	1) Single-phase start.	1) Check power source cables, motor cables, fuses and switch contactors to find the broken wires or connection failures then solve the problems.
	2) Motor is overloaded or locked.	2) Adjust load value to rated one and deal with driven machine failure.

Electrical failure	Cause	Solution
3 - After energized, motor cannot start but has noise	1) Motor is overloaded or locked.	1) Inspect equipment and shoot the trouble.
	2) Check power sources so all phases have correct voltage.	2) Check connection of supply and/or feed. Replace fuse, fasten the loosened bolts the terminals, check the power source cables etc. with an instrument suitable for this work.
	3) too low voltage.	3) Change to Delta connection if it was misconnected as Star; Contact the power supply station if it is caused by power source; Adopt bigger cables if it is caused by the voltage drop of cables.
	4) Stearin grease or tight fitness for small-sized motors.	4) Select applicable grease and increase assembly quality.
4 - Live motor enclosure	1) Mix the power source cables and earthing cables.	1) Correct the mistake.
	2) Stator winding becomes damp and insulation ages severely.	2) Dry the motor and renew the aged insulation.
	3) Lead cables and terminal box are earthed.	3) Bind or renew outlet insulation and repair terminal box.
5 - Hard to start and speed lower than rated speed at full load	1) Power source voltage is too low.	1) Measure the power voltage at input points with a voltmeter or avometer and find the solution.
	2) Delta connection is misconnected as Star.	2) Change Star connection back to Delta.
	3) The rotor is coming off or broken.	3) Check and repair the rotor.
	4) Coils are more than original when rewind the winding.	4) Rewind the coils according to correct numbers.
	5) Winding gets moist or motor suffers from rain.	5) Heat to dry the motor.
	6) Aged winding insulation.	6) Coat the winding insulation or replace the insulation.
6 - Low insulation resistance	1) Winding gets moist or motor suffers from rain.	1) Heat to dry the motor.
	2) Aged winding insulation.	2) Coat the winding insulation or replace the insulation.

Electrical failure	Cause	Solution
7 - Abnormal noise during operation	1) Bearings are worn.	1) Repair or replace bearings.
	2) Stator or rotor core is loose.	2) Find the cause of vibration, re-press the core.
	3) Voltage is too high or unbalanced.	3) Measure the voltage on power source, find the cause and solve it.
	4) Bearing short of grease.	4) Clean the bearing and replenish grease with the amount of one-third to half of the bearing chamber volume.
	5) Fan contacts fan cover or the ventilation is blocked.	5) Repair fan and fan cowl and clear up ventilation area.
8 - Motor overheat or smoking	1) Too high power source voltage makes flux density in stator core oversaturated and results in high temperature rise.	1) If supply voltage exceeds standard value too much, contact power supply department.
	2) Too low power source voltage makes high temperature rise at full load.	2) Replace the cables by bigger ones if it is caused by voltage drop. Contact the power supply department if it is caused by low voltage.
	3) Stator and rotor interfered.	3) If it is caused by larger bearing clearance, replace the bearing. If it is caused by the shaft which is bent, align it. Repair the core if it is loose or deformed.
	4) Motor overload or big resistance from the driven machine, which lead to high temperature.	4) Solve the trouble of driven machine, reduce load if exceeding rated current as per the indication, adopt a larger motor or increase the capacity.
	5) Frequently starting or too many reverse rotations.	5) Reduce number of starts and reverse rotations or adopt an applicable motor.
	6) Fan failure or poor ventilation.	6) Check the fan to see whether it is damaged or the blades are deformed or not fixed properly. Replace the fan if necessary.
9 - Unbalanced no load current at big difference	1) Unbalanced power source voltage.	1) Measure the source voltage to find the cause.
	2) Winding failures such as short circuit coils, wrongly connected coils etc.	2) Disassemble the motor to check polarity and failures in windings, correct polarity or shoot the troubles.
	3) Coils and turns are not equally distributed after rewind the stator winding.	3) Rewind the stator winding as per the instructions.

Mechanical failure	Cause	Solution
1 - Vibration	1) Worn bearing or the poor bearing clearance.	1) Check bearing clearance.
	2) Air gaps are not even.	2) Adjust air gap to meet specifications.
	3) Unbalanced fan or rotor.	3) Find out the cause and balance the fan, the rotor or the motor.
	4) The rigidity of enclosure or the foundation is not strong enough.	4) Find the root to reinforce the enclosure rigidity or foundation. Align the motor and fasten it.
	5) Shaft is bent.	5) Align the shaft.
	6) Rotor core is deformed or loose.	6) Adjust the iron core and then stack it again.
	7) Loose mounting/fixing bolts.	7) Fasten the bolts or replace them by qualified ones.
2 - High bearing temperature	1) Either too much or too less grease.	1) Replenish the bearing with grease according to operation instructions.
	2) Poor grease with impurities.	2) Check the impurities of grease and change to clean grease.
	3) Oil seal is fit too tight.	3) Repair or replace the oil seal.
	4) Eccentric inner bearing cap contacts the shaft.	4) Repair inner bearing cap to keep proper gap with shaft.
	5) End shields or bearing caps are not assembled properly.	5) Put end shield or bearing cap into spigot by correct process and then fasten bolts evenly.
	6) Bearings are worn or dirt etc.	6) Replace the damaged bearing. Clean the dirt bearings thoroughly and replenish grease.
	7) Eccentric coupling connection or too tight belt.	7) Align the motor with driven machine and adjust the tension of belt.
	8) Improper bearing size.	8) Select proper bearing size.
	9) Too big or too less bearing clearance.	9) Replace the bearing.

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